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Estimating Compact Yet Rich Tree Insertion Grammars

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Abstract

We present a Bayesian nonparametric model for estimating tree insertion grammars (TIG), building upon recent work in Bayesian inference of tree substitution grammars (TSG) via Dirichlet processes. Under our general variant of TIG, grammars are estimated via the Metropolis-Hastings algorithm that uses a context free grammar transformation as a proposal, which allows for cubic-time string parsing as well as tree-wide joint sampling of derivations in the spirit of Cohn and Blunsom (2010). We use the Penn treebank for our experiments and find that our proposal Bayesian TIG model not only has competitive parsing performance but also finds compact yet linguistically rich TIG representations of the data.

1 Introduction

There is a deep tension in statistical modeling of grammatical structure between providing good expressivity — to allow accurate modeling of the data with sparse grammars — and low complexity — making induction of the grammars and parsing of novel sentences computationally practical. Recent work that incorporated Dirichlet process (DP) nonparametric models into TSGs has provided an efficient solution to the problem of segmenting training data trees into elementary parse tree fragments to form the grammar (Cohn et al., 2009; Cohn and Blunsom, 2010; Post and Gildea, 2009). DP inference tackles this problem by exploring the space of all possible segmentations of the data, in search for fragments that are on the one hand large enough so that they incorporate the useful dependencies, and on the other small enough so that they recur and have a chance to be useful in analyzing unseen data.

The elementary trees combined in a TSG are, intuitively, primitives of the language, yet certain linguistic phenomena (notably various forms of modification) “split them up”, preventing their reuse, leading to less sparse grammars than might be ideal. For instance, imagine modeling the following set of structures:

- \([NP \text{ the } NN [NN \text{ president} \text{ of the university}] \text{ who resigned yesterday}]\)
- \([NP \text{ the } NN \text{ former } NN [NN \text{ president} \text{ of the university}]\])
- \([NP \text{ the } NN [NN \text{ president} \text{ who resigned yesterday}]\])

A natural recurring structure here would be the structure “\([NP \text{ the } NN \text{ president}]\)”, yet it occurs not at all in the data.

TSGs are a special case of the more flexible grammar formalism of tree adjoining grammar (TAG) (Joshi et al., 1975). TAG augments TSG with an \textit{adjunction operator} and a set of \textit{auxiliary trees} in addition to the substitution operator and initial trees of TSG, allowing for “splicing in” of syntactic fragments within trees. In the example, by augmenting a TSG with an operation of adjunction, a grammar that hypothesizes auxiliary trees corresponding to adjoining “[NN \text{ former } NN]”, “[NN \text{ NN of the university}]”, and “[NN \text{ NN who resigned yesterday}]” would be able to reuse the basic structure “\([NP \text{ the } NN \text{ president}]\)”. Unfortunately, TAG’s expressivity comes at the cost of greatly increased complexity. Parsing complexity for unconstrained TAG scales as \(O(n^6)\), im-
practical as compared to CFG and TSG’s $O(n^3)$. In addition, the model selection problem for TAG is significantly more complicated than for TSG since one must reason about many more combinatorial options with two types of derivation operators. This has led researchers to resort to heuristic grammar extraction techniques (Chiang, 2000; Carreras et al., 2008) or using a very small number of grammar categories (Hwa, 1998).

Hwa (1998) first proposed to use tree-insertion grammars (TIG), a kind of expressive compromise between TSG and TAG, as a substrate on which to build grammatical inference. TIG constrains the adjunction operation so that spliced-in material falls completely to the left or completely to the right of the splice point. By restricting the form of possible auxiliary trees to only left or right auxiliary trees in this way, TIG remains within the realm of context-free formalisms (with cubic complexity) while still modeling rich linguistic phenomena (Schabes and Waters, 1995). Figure 1 depicts some examples of TIG derivations.

Sharing the same intuitions, Shindo et al. (2011) have provided a previous attempt at combining TIG and Bayesian nonparametric principles, albeit with severe limitations. Their TIG variant (which we will refer to as TIG$_0$) is highly constrained in the following ways.

1. The foot node in an auxiliary tree must be the immediate child of the root node.
2. Only one adjunction can occur at a given node.

The increased expressivity of our TIG variant is motivated both linguistically and practically. From a linguistic point of view: Deeper auxiliary trees can help model large patterns of insertion and potential correlations between lexical items that extend over multiple levels of tree. Combining left and right auxiliary trees can help model modifiers of the same node from left and right (combination of adjectives

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Throughout the paper, we will refer to the depth of an auxiliary tree to indicate the length of its spine.

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This can be seen by the fact that tree-path languages under TAG are context free, whereas they are regular for TSG. (Schabes and Waters, 1995)
and relative clauses for instance). Simultaneous insertion allows us to deal with multiple independent modifiers for the same constituent (for example, a series of adjectives). From a practical point of view, we show that an induced TIG provides modeling performance superior to TSG and comparable with TIG0. However we show that the grammars we induce are compact yet rich, in that they succinctly represent complex linguistic structures.

2 Probabilistic Model

In the basic nonparametric TSG model, there is an independent DP for every grammar category (such as \( c = NP \)), each of which uses a base distribution \( P_0 \) that generates an initial tree by making stepwise decisions.

\[
G_c^{\text{init}} \sim \text{DP}(\alpha_c^{\text{init}}, P_0^{\text{init}}(\cdot | c))
\]

The canonical \( P_0 \) uses a probabilistic CFG \( \tilde{P} \) that is fixed a priori to sample CFG rules top-down and Bernoulli variables for determining where substitutions should occur (Cohn et al., 2009; Cohn and Blunsom, 2010).

We extend this model by adding specialized DPs for left and right auxiliary trees.\(^3\)

\[
G_c^{\text{right}} \sim \text{DP}(\alpha_c^{\text{right}}, P_0^{\text{right}}(\cdot | c))
\]

Therefore, we have an exchangeable process for generating right auxiliary trees

\[
p(a_j | a_{<j}) = \frac{n_{a_j} + \alpha_c^{\text{right}} P_0^{\text{right}}(a_j | c)}{j + 1 + \alpha_c^{\text{right}}} (1)
\]

as for initial trees in TSG.

We must define three distinct base distributions for initial trees, left auxiliary trees, and right auxiliary trees. \( P_0^{\text{init}} \) generates an initial tree with root label \( c \) by sampling CFG rules from \( \tilde{P} \) and making a binary decision at every node generated whether to leave it as a frontier node or further expand (with probability \( \beta_c \) (Cohn et al., 2009). Similarly, our \( P_0^{\text{right}} \) generates a right auxiliary tree with root label \( c \) by first making a binary decision whether to generate an immediate foot or not (with probability \( \gamma_c^{\text{right}} \)), and then sampling an appropriate CFG rule

\[
(\text{VP (., ,) (VP PP (VP (., ,) VP*)))}
\]

\[
(\text{VP SBAR (WHADVP (WRB (WRB When) ) ) S (VP (., ,) VP*)})
\]

\[
(\text{VP (PP (IN For) (NP NN ) (VP (., ,) VP*))})
\]

\[
(\text{VP ADV (VP (., ,) VP*)})
\]

\[
(\text{IN (ADV VP (RB particularly) ) ) IN*)}
\]

\[
(\text{NP PP (NP (CC and) (NP PP PP*)))}
\]

Figure 3: Example left auxiliary trees that occur in the top derivations for Section 23. Simultaneous insertions occur most frequently for the labels VP (85 times), NNS (21 times), NNP (14 times).

3 Inference

Given this model, our inference task is to explore optimal derivations underlying the data. Since TIG derivations are highly structured objects, a basic sampling strategy based on local node-level moves such as Gibbs sampling (Geman and Geman, 1984) would not hold much promise. Following previous work, we design a blocked Metropolis-Hastings sampler that samples derivations per entire parse trees all at once in a joint fashion (Cohn and Blunsom, 2010; Shindo et al., 2011). This is achieved by proposing derivations from an approximating distribution and stochastically correcting via accept/reject to achieve convergence into the correct posterior (Johnson et al., 2007).

Since our base distributions factorize over levels of tree, CFG is the most convenient choice for a
Figure 4: Transformation CFG rules that represent infinite base distributions. $P_0^{\text{init}}$ is taken from Cohn and Blunsom (2010). Underscored labels (such as $\text{NP}^{\text{right}}$ as opposed to $\text{NP}^{\text{init}}$) are used to differentiate the pre-insertion nodes in Figure 2 from the post-insertion ones. $P_0^{\text{init}}$ rules are omitted for brevity and mirror the $P_0^{\text{right}}$ rules above.

Figure 5: EVALB results after training on Section 2 and testing on Section 23. Note that TIG finds a compact yet rich representation. Elementary tree counts are based on ones with count $> 1$.

5 Conclusion

We described a nonparametric Bayesian inference scheme for estimating TIG grammars and showed the power of TIG formalism over TSG for returning rich, generalizable, yet compact representations of data. The nonparametric inference scheme presents a principled way of addressing the difficult model selection problem with TIG which has been prohibitive in this area of research. TIG still remains within context free and both our sampling and parsing techniques are highly scalable.

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References


