



Instrumented cardiac microphysiological devices via multimaterial three-dimensional printing

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1 Instrumented cardiac microphysiological devices via multi-material 3D printing2
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1 **Biomedical research has relied on animal studies and conventional cell cultures for**
2 **decades. Recently, microphysiological systems (MPS), also known as *organs-on-chips*, that**
3 **recapitulate the structure and function of native tissues *in vitro* have emerged as a**
4 **promising alternative[1]. However, current MPS typically lack integrated sensors and their**
5 **fabrication requires multi-step lithographic processes[2]. Here, we introduce a facile route**
6 **for fabricating a new class of instrumented cardiac microphysiological devices via multi-**
7 **material 3D printing. Specifically, we designed six functional inks, based on piezo-resistive,**
8 **high conductance, and biocompatible soft materials that enable integration of soft strain**
9 **gauge sensors within micro-architectures that guide the self-assembly of physio-mimetic**
10 **laminar cardiac tissues. We validated that these embedded sensors provide non-invasive,**
11 **electronic readout tissue of contractile stresses, inside cell incubator environments. We**
12 **further apply these devices to study drug responses, as well as the contractile development**
13 **of human stem cell derived laminar cardiac tissues over four weeks.**

14 Current MPS models of muscle tissue rely on microscopy coupled with optical tracking
15 analysis for assessing tissue contractile stress. For instance, muscular thin film (MTF) assays
16 track changes in curvature of soft cantilever substrates induced by the contraction of a laminar
17 tissue [3], and micro-post assays measure the deflection of pillars supporting a micro-tissue [4].
18 Although these assays have proven valuable for short-term modeling of human disease and
19 small-scale drug screening applications [1, 5, 6], they are not well suited for higher throughput or
20 longer term studies. Moreover, biomimetic microsystems are currently fabricated using soft-
21 material lithography-based techniques that require multiple steps, masks and dedicated tools[4,
22 7-9], which hinders rapid prototyping and customization. By contrast, multi-material 3D

1 printing of viscoelastic inks enables a wide range of functional, structural and biological
2 materials to be patterned and integrated in a single programmable manufacturing step [10-14].

3 Here, we introduce a fully 3D printed and instrumented microphysiological device that
4 provides continuous electronic readout of the contractile stress of multiple laminar cardiac
5 micro-tissues (Fig. 1a-b). Each device contains three key features: *i*) multilayer cantilevers,
6 composed of a base layer, an embedded strain sensor, and a tissue-guiding layer, *ii*) electrical
7 interconnects for readout, and *iii*) eight independent wells (Fig. 1c-i). The tissue-guiding layer
8 promotes self-assembly of engineered physio-mimetic laminar tissues from neonatal rat
9 ventricular myocytes (NRVMs) and human induced pluripotent stem cell derived
10 cardiomyocytes (hiPS-CMs). Our microphysiological device facilitates tissue culture and non-
11 invasive analyses of tissue contractile strength over several weeks, and facilitates drug studies
12 inside a controlled incubator environment.

13 To create this integrated device, six materials are patterned sequentially via direct ink
14 writing multi-material 3D printing. To allow material integration at the microscale, the substrate
15 topology and *x-y-z* positions of four individually addressable nozzles are determined by an
16 automated calibration process (see supplementary movie S1). After this calibration, the device is
17 printed in a single continuous procedure (Fig. 1c-i and supplementary movies S2-3).

18 The stress generated by laminar cardiac tissues is limited to 1-15kPa [5, 8]. Hence, to
19 match this range, both the thickness and stiffness of each cantilever layer must be minimized.
20 Towards this objective, we designed a series of highly dilute polymer-based inks. Their low
21 solids content ensures patterning of thin individual layers (0.5 – 6.5 μ m in thickness).
22 Additionally, by tuning the evaporation rate of the carrier solvent solution, the ink viscosity and
23 corresponding wetting and spreading behavior is controlled to achieve the desired lateral

1 dimensions (supplementary Fig. S1-2). Using these inks, we first printed 0.5 μm dextran films
2 (Fig. 1c), which serve as biocompatible, water-soluble sacrificial release layers that allow the
3 final cantilevers to detach from the substrate and deflect freely. Next, using dilute thermoplastic
4 polyurethane (TPU) inks, 3 μm thick cantilever bases, 6.5 μm thick strain gauge wires and 1.5 μm
5 thick wire covers are printed in steps 2-4, respectively (Fig. 1d-f). The cantilever base and wire
6 covers are printed using an unfilled TPU ink, while the strain gauge wires are printed using a
7 TPU ink filled with 25wt% carbon black nanoparticles (CB:TPU). The printed TPU-based
8 features exhibited elastic mechanical properties with Young's modulus of 1.6MPa
9 (supplementary Fig. S3), while CB:TPU features readily cured to form an elastic piezo-resistive
10 material with Young's modulus of 8.8MPa and resistivity of 1.19 $\Omega\cdot\text{cm}$ (supplementary Fig. S3-
11 7). Several alternative fillers were investigated, including metals particles [15] and carbon
12 nanotubes[16]. However, we found that carbon black imparts the best combination of ink
13 rheology, low stiffness and sensor hysteresis.

14 The remainder of the microphysiological device is printed using concentrated viscoelastic
15 inks optimized for deposition of self-supporting structures (supplementary Fig. S8-9). Using a
16 soft viscous PDMS ink (Young's modulus of 1.28MPa, see Supplementary Fig. S3), ~60 μm
17 wide filaments are patterned on top of each cantilever (Fig. 1g). These comprised the majority of
18 the cantilever thickness and served as direct support below the physio-mimetic laminar cardiac
19 tissue. Next, electrical leads and contact pads are printed using a high-conductivity, silver
20 particle-filled, polyamide (Ag:PA) ink (Fig. 1h). Upon drying, the printed wires exhibit an
21 electrical resistivity of 6.6x10⁻⁵ $\Omega\cdot\text{cm}$ (supplementary Fig. S4), which ensures that the primary
22 electrical resistance of the final device arose from the embedded CB:TPU strain gauges. Finally,
23 the wire leads are covered with an insulating layer and eight individually addressable wells are

1 printed using either a PDMS ink or biocompatible rigid thermoplastic polymers such as
2 polylactid acid (PLA) or acrylonitrile butadiene styrene (ABS). The rigid polymers can be
3 preferable for drug study applications, as they are less prone to bulk absorption of hydrophobic
4 drugs than PDMS [17] (Fig. 1i, supplementary Fig. S10). After printing, the devices are cured at
5 100°C and subsequently seeded with cardiomyocytes, which self-assemble into laminar tissues
6 mimicking the structure of the native heart.

7 The musculature of the heart is composed of highly organized, structurally and
8 electrically anisotropic layers [18]. To recapitulate this architecture *in vitro*, we printed a range
9 of grooved microstructures by varying the spacing between curved $\sim 20\mu\text{m} \times 60\mu\text{m}$ (height x
10 width) filaments and assessed their ability to guide the self-assembly of anisotropic laminar
11 NRVM tissues (Fig. 2). We evaluated the degree of tissue structural anisotropy using
12 immunofluorescent imaging of sarcomeric α -actinin and quantification of the sarcomere
13 Orientational Order Parameter (OOP) (Fig. 2a-f, supplementary Fig. S11) [19]. All substrates
14 showed an OOP > 0.2 indicative of non-random sarcomere alignment. The highest OOP ~ 0.5
15 was observed for $60\mu\text{m}$ filament spacing. Similarly, $60\mu\text{m}$ filament spacing gave rise to the
16 highest degree of electrophysiological anisotropy in the laminar NRVM tissues (Fig. 2g-i,
17 supplementary Movies S4-7). For this spacing, action potential propagation was 2.7 times faster
18 parallel to the grooves compared to the transverse direction. These data are in agreement with the
19 longitudinal to transverse velocity ratio of 2.1 observed in the native ventricle [18]. Also, these
20 anisotropic laminar tissues gave rise to unidirectional and concerted cantilever deflection and
21 displayed the highest contractile stresses in the final devices (supplementary Fig. S12-14).
22 Collectively, these results demonstrate that our printing technique can be employed to engineer
23 laminar cardiac tissues with a range of ordered architectures. Notably, the OOP and

1 electrophysiology data closely matched values obtained using semi-manual micro-contact
2 printing and molding techniques [7, 20].

3 To accurately measure the stress exerted by the physio-mimetic laminar cardiac tissues,
4 the embedded strain gauges within each cantilever must produce a reliable and detectable signal.
5 We therefore evaluated the electro-mechanical properties of CB:TPU in a series of uniaxial
6 strain tests (Fig. 3a-d, supplementary Fig. S5-7). To mimic the strains exerted by tissue
7 contraction, 1-3Hz triangular strains of 0.1% were applied to CB:TPU gauges. In this strain
8 range, the gauges displayed a linear strain-resistance relationship with limited hysteresis and a
9 corresponding gauge factor of 2.51 ± 0.09 . In order to accurately convert resistance signals to
10 stresses generated by the laminar cardiac tissues, we established a mechanical model of the
11 cantilevers based on a multilayer version of Stoney's equation (Fig. 3e-f and supplementary
12 information). The mechanical model relies on the dimensions and Young's moduli of each layer
13 of the cantilever as well as the CB:TPU gauge factor. The model provides linear conversion
14 factors between the relative changes in gauge resistance, changes in cantilever radius of
15 curvature, and in turn, the longitudinal stresses generated by the laminar cardiac tissues.
16 Applying these conversion factors, we obtained tissue twitch stress (σ_{twitch}), the differences
17 between the systolic and diastolic stress, in the range of 7-15kPa for laminar NRVM tissues, akin
18 to prior reports [3, 7]. To further verify the model, we compared the sensor readout with stress
19 values concurrently obtained through optical tracking of cantilever deflection, and obtained
20 highly similar stress values (Fig. 3g-h, supplementary Fig. S12-14, supplementary Movie S8-11).
21 Yet, we observed one discrepancy between the optical tracking and electrical readout: at the
22 initiation of tissue contraction, a small decrease in gauge resistance is seen, prior to the increase
23 caused by cantilever deflection. We attribute this decrease to a brief axial compression of the

1 gauge wire occurring during initial tissue contraction, while cantilever deflection is counteracted
2 by inertial and viscous forces. Notably, this observation does not influence tissue twitch stress
3 values. Together, these results demonstrate that the CB:TPU strain-gauges embedded in our fully
4 printed platform provide reliable readouts of tissue contractile stress.

5 Data acquisition from cardiac microphysiological systems based on optical readout is
6 laborious, requires dedicated microscopy setups, semi-automated image analysis software, and is
7 limited by the image readout file sizes [4, 5]. By contrast, our fully printed and instrumented
8 cardiac devices provide a direct, non-invasive electronic readout of contractile stresses.
9 Therefore, we could perform dose response studies of drugs that influence contraction strength or
10 beat rate, directly inside a cell incubator, an ideal *in vitro* environment (Fig. 3i-j, supplementary
11 Fig. S15-18). As examples, we carried out cumulative drug dose studies with the L-type calcium
12 channel blocker verapamil and the β -adrenergic agonist isoproterenol. For laminar NRVM
13 tissues we observed a negative inotropic response to verapamil, with an apparent EC_{50} of
14 $1.15 \times 10^{-6} M$ when paced at 1Hz (Fig. 3i). We also observed a negative chronotropic effect for
15 spontaneously beating tissues (supplementary Fig. S17), in good agreement with prior studies on
16 isolated postnatal whole rat hearts [21]. Similarly, we observed a positive chronotropic response
17 to isoproterenol for spontaneously beating laminar tissues, matching previous studies of
18 engineered NRVM micro-tissues [4] (supplementary Fig. S18). For hiPS-CM-based laminar
19 tissues, we observed a positive inotropic response to isoproterenol, with an apparent EC_{50} of
20 $2.69 \times 10^{-9} M$ when paced at 2Hz (Fig. 3j), resembling studies based on embryonic stem cell
21 derived cardiomyocyte tissue [22].

22 Beyond facilitating acute drug studies, our platform is well suited for extended studies to
23 identify gradual changes in the contractile stress of engineered cardiac tissues, which can occur

1 over the course of multiple weeks [22, 23]. As a demonstration, we studied the *in vitro*
2 contractile development of laminar tissues based on hiPS-CMs over the course of 28 days (Fig.
3 4a-g). During this period, the longitudinal contractile stress initially increased 4-fold from day 2
4 to 4, followed by a more gradual increase (Fig. 4a-b). Similarly, the spontaneous beating rate
5 decreased (Fig. 4c), indicative of increased maturity [24]. The changes in twitch stress are
6 mirrored by a structural development of the laminar hiPS-CM tissues (Fig. 4d-g, supplementary
7 Fig. S19). From day 2 to day 14 the sarcomere OOP increased from 0.11 to 0.32 (Fig. 4e), while
8 the Sarcomere Packing Density (SPD, a measure of sarcomere periodic organization) increased
9 from 0.07 to 0.2 (Fig. 4f), indicating that hiPS-CMs undergo sarcomerogenesis and
10 myofibrillogenesis during culture [19]. Importantly, from day 14 to day 28, a significant increase
11 in sarcomere length from 1.7 μ m to 1.8 μ m was observed (Fig. 4g), indicative of a more mature
12 tissue [25].

13 While traditional muscular thin films mimic essential features of the cardiac architecture,
14 cell-cell contacts are confined to a single cell layer. By contrast, a number of *in vitro* cardiac
15 tissue models composed of thicker micro-tissues have been reported [26-28]. To illustrate the
16 versatility of our 3D printing methodology, we modified the MPS device to support thicker
17 micro-tissues, approximately 4 cell layers thick (supplementary Fig. S21-24). This thickness
18 matches that of the myocyte layers in a mammalian heart (i.e., ~ 4 cells in thickness per layer,
19 each layer separated by connective tissue) [29]. To balance the increased contractile stress and
20 mitigate tissue delamination, we printed thicker cantilevers that contained ~100 μ m tall micro-
21 pin arrays with tunable areal density (Fig. 4h-i, supplementary movie S13-15). Despite these
22 modifications to both the cardiac tissue and cantilevers, the tissue remains orders of magnitude
23 softer than the substrate. Hence, the basic assumptions of the mechanical model remain valid,

1 and the sensor signal is directly proportional to mean tissue stress (see supplementary
2 information). We carried out proof of principle isoproterenol and verapamil drug studies to
3 illustrate the functional relevance of these thicker NRVM based tissues (Fig. 4j-k). We observed
4 the expected positive and negative inotropic responses with apparent EC_{50} values comparable to
5 earlier data from engineered 3D NRVM tissues and isolated postnatal whole rat hearts [21, 28].

6 Through multi-material 3D printing of a series of customized inks, we demonstrated the
7 automated design and fabrication of instrumented cardiac microphysiological devices. The
8 integrated sensors drastically simplify data acquisition and long term functional studies.
9 Leveraging the ability to track the temporal development in tissue mechanics will enable new
10 insights into tissue morphogenesis, pathogenesis, and drug-induced structural and functional
11 remodeling. Our digital manufacturing approach is quite versatile, allowing for fabrication of a
12 range of instrumented microphysiological devices. Notably, our approach facilitates rapid
13 customization to match device geometries, mechanical and biochemical properties to a specific
14 diseased state or a unique patient derived cell source. Our programmable microfabrication
15 approach opens new avenues for *in vitro* tissue engineering, toxicology and drug screening
16 research.

17

18

1 **Methods**

2 *Ink formulations*

3 The following ink formulations were used: *Dextran ink*: 10g/ml Dextran (Sigma-Aldrich) was
4 dissolved in 9:1 v:v, water: isopropanol, *TPU ink*: TPU 15wt% Elastollan 35A (BASF) dissolved
5 in 4:1 v:v tetrahydrofuran:dimethylformamide, *CB:TPU ink*: TPU 15wt% Elastollan 35A, 5wt%
6 carbon black (Vulcan XC72R, Cabot) dissolved in 4:1 v:v tetrahydrofuran:dimethylformamide.
7 *Ag:Pa ink*: 50g Silver flakes (5-8 μ m) mixed with 5.2g 30wt% versamid 973 solution (BASF)
8 dissolved in pentanol, mixed with an additional 2.72g of pentanol. *Soft PDMS Ink*: SE1700
9 (Dow-Corning) with 1:25 curing agent based ratio was applied for cantilever covers, micro-pins
10 and micro-wells. *Rigid PDMS ink*: SE1700 (Dow-Corning), with 1:10 curing agent weight ratio,
11 mixed 1:5 wt:wt with Sylgard 184 1:10 curing agent weight ratio (Dow-Corning) is used for
12 wells and covers, or as gasket adhesive below PLA or ABS wells and covers.

13 *Print procedure with integrated profiling*

14 Printing was carried out using a three-axis motion-controlled stage (Aerotech) with 4
15 independent z-axes. Prior to printing, a custom automation system was applied to determine the
16 substrate topology and relative x-y-z nozzle positions using an integrated laser profilometer,
17 three CCD micrometers (Keyence), and custom machined fixtures. G-code generation and
18 custom automation scripts were programmed using open-sourced python libraries (Mecode).
19 Extrusion was carried out using syringes, dispense tips, and a digital pneumatic regulator (EFD).
20 Dispense tip diameters: *TPU ink*: 100 μ m, *CB:TPU ink*: 200 μ m, *Ag:PA ink*: 250 μ m, *Soft PDMS*
21 *ink*: 30 μ m, *Rigid PDMS ink*: 410 μ m. For Dextran ink a refillable contact-pressure sensitive pen
22 (0.7mm tip, Montana) was utilized as deposition nozzle.

23

1 *Device cell seeding and culture*

2 Prior to cell seeding, devices were sterilized by UV-Ozone exposure for 8mins. Subsequently,
3 wells were incubated with a 50 μ g/ml solution of Fibronectin (BD biosciences) in PBS for 1hr.
4 Fibronectin solution was aspirated and wells seeded with either primary NRVMs at a seeding
5 density of a seeding density of 140k/cm² in 10% FBS in media 199 (Life Technologies) or hiPS-
6 CMs (Cor4U, Axiogenesis, Germany) at 220k/cm² in designated Commercial Cor4U media
7 (Axiogenesis, Germany). For thicker tissue version, NRVM are seeded at 1M/cm² adding cold
8 BD MatrigelTM (BD biosciences) to final concentration 0.45-0.6mg/ml, thus below gelling
9 concentration. NRVMs were acquired from Sprague Dawley rats ($n \geq 10$ litters, per harvest)
10 applying procedures approved by the Harvard University Animal Care and Use Committee,
11 described in detail in supplementary information. hiPS-CMs were thawed, pre-plated and seeded
12 following guidelines from supplier, as detailed in supplementary information. Cell media was
13 changed at least every second day, applying 2% FBS in media 199 (Life Technologies) for
14 NRVM culture, and designated Cor4U media for hiPS-CM culture.

15 *Data acquisition*

16 Data collection was performed using custom machined holder connecting device to a Keithley
17 Multichannel DMM 3706a. Readouts were obtained either as 2-wire resistance recordings
18 sampling at ≥ 60 Hz. A custom MATLAB (*MathWorks, Natick, MA*) code was applied for
19 quantifying relative resistance changes upon tissue contraction applying peak detection and
20 comparison with local baseline, for electrically paced samples a median filter (5) was applied.
21 Linear conversion constants between relative resistance change, cantilever curvature and stress
22 generated by tissue, were established using designated mechanical model.

23

1 *Isoproterenol and verapamil Cumulative drug dose studies*

2 Cumulative dosing of isoproterenol or verapamil (Sigma-Aldrich) cardiac drugs was performed
3 on laminar NRVM and hiPS-CM tissues inside incubator. 700ul serum free media was added to
4 each well prior to drug dose experiments. A dilution series of the drugs in media (Life
5 Technologies) was sequentially added in 7ul doses. Tissue was incubated for 10mins for each
6 dose, prior to recording. For each dose at least 30s were recorded per channel. Isoproterenol
7 stocks were kept at 4°C prior to dosing. Pacing was applied using custom platinum wire
8 electrodes. Each n denotes separate device wells with isolated tissue, sensor and media.

9 *Tissue immuno-staining and structural analysis*

10 All immunocytochemistry procedures were conducted at room temperature. Samples were first
11 fixed with 4% PFA/PBS (v/v) solution for 15mins and then permeabilized with 0.05 % Triton-
12 X/PBS (v/v) solution for 10mins. Subsequently, samples were incubated for 1hr with a
13 monoclonal sarcomeric α -actinin (clone EA-53; Sigma-Aldrich) primary antibody, washed three
14 times in PBS, and finally counterstained with: Alexa Fluor 488-conjugated anti-mouse secondary
15 antibody, Alexa Fluor 633-conjugated Phalloidin and DAPI (Invitrogen). Samples were imaged
16 using confocal microscopy, acquiring projected Z-stack images of the wavy laminar tissues. The
17 alignment and overall spatial organization of α -actinin positive structures in the immunostained
18 digital images were evaluated with custom MATLAB (*MathWorks, Natick, MA*) code as
19 previously described [19].

20 *Optical mapping experiments to determine tissue electrophysiology*

21 AP propagation velocities for the engineered NRVM cardiac tissues were monitored using a
22 modified tandem-lens microscope (*Scimedia, Costa Mesa, CA*) equipped with a high speed
23 camera (*MiCAM Ultima, Scimedia, Costa Mesa, CA*), a plan APO 1X objective, a collimator

1 (*Lumencor, Beaverton, OR*) and a 200mW Mercury lamp (*X-Cite exacte, Lumen Dynamics,*
2 *Canada*). After 4 days culture *in vitro*, 10mmx10mm engineered laminar NRVM tissues were
3 incubated with 4 μ M solution of a photovoltaic dye, RH237. (Invitrogen, Carlsbad, CA) for
4 5mins at 37 °C, and rinsed with Tyrode's solution prior to recording. Recordings were acquired
5 at a frame rate of 200 Hz. Electrical point stimulation was applied to the corner of the tissue using
6 two U-shaped platinum electrodes (*Sigma-Aldrich, St. Louis, MO*) located 0.5-1mm above the
7 tissue, applying 1-2Hz, 5-10V pulses of 10ms duration using a pulse generator (*MyoPacer Cell*
8 *Stimulator, IonOptix, Milton, MA*). Post-processing of data was conducted with custom
9 MATLAB (*MathWorks, Natick, MA*) code as previously described [30]. A spatial filter with 3 \times
10 3 pixels was applied to improve the signal-noise ratio similar. Activation time was calculated as
11 the average time to maximum upstroke slope of pulses when continuously paced at 2Hz during
12 in a 5s recording window.

13 *Statistical analysis*

14 For analysis of tissue SPD, OOP and sarcomeric length, One Way Analyses for Variance
15 between the compositional groups were conducted using SigmaPlot (v12.0, Systat Software
16 Inc.). All data sets passed Shapiro-Wilk normality tests and equal variance tests. For pairwise
17 comparison Holm-Sidak method was applied. For all statistical analyses, p-values less than 0.05
18 were considered statistically significant. Sample sizes were chosen based on previous studies
19 applying muscular thin film assays [19, 20, 30].

20 *Code availability*

21 Custom MATLAB scripts for signal detection and stress calculation can be found as
22 supplementary information.

23

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16 notwithstanding any copyright notation hereon.

17

18 Competing Financial Interests

19 The authors declare no competing financial interests

20

21

1 Author Contributions

2 J.U.L., T.A.B, J.A.L. and K.K.P designed the study. J.U.L. and T.A.B. designed device. T.A.B.
3 coded 3D-print procedure and automation. J.U.L, T.A.B, A.K., and A.D.V. developed and
4 characterized the printable materials. J.U.L, A.D.V. and T.A.B, optimized and printed devices.
5 P.H.C. performed NRVM harvest and prepared culturing media. J.U.L., M.Y. and A.P.N.
6 performed NRVM culture, drug-dose experiments, and data analysis. M.Y. and J.U.L. conducted
7 hiPS-CM culture, experiments and data analysis. F.S.P and J.U.L. performed tissue staining,
8 confocal imaging, and O.O.P. analysis. S-J.P., J.U.L. conducted optical mapping experiments
9 and analysis. H.Y. and J.J.V. developed mechanical model of device. J.U.L, T.A.B., J.A.L, and
10 K.K.P prepared illustrations and wrote manuscript. F.S.P and A.D.V contributed to manuscript.

11

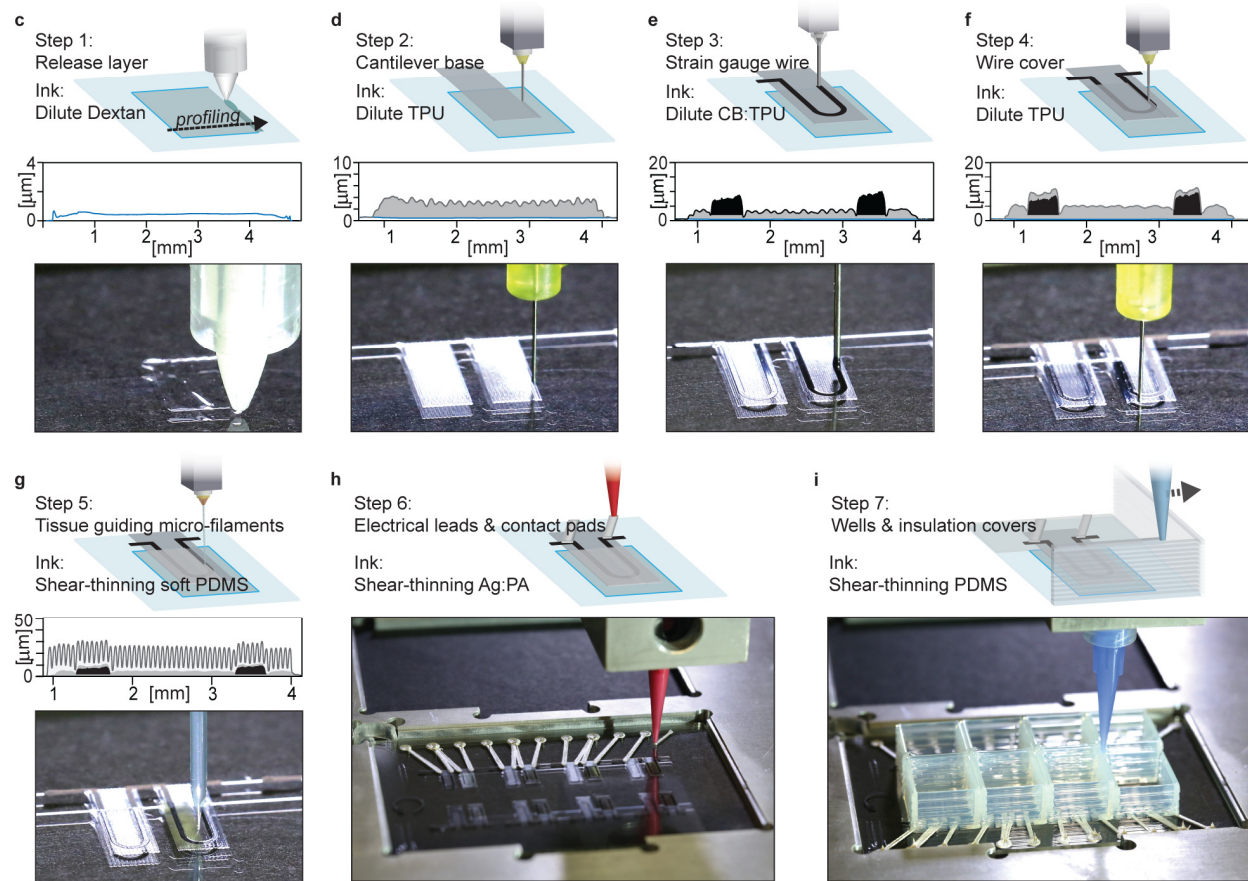
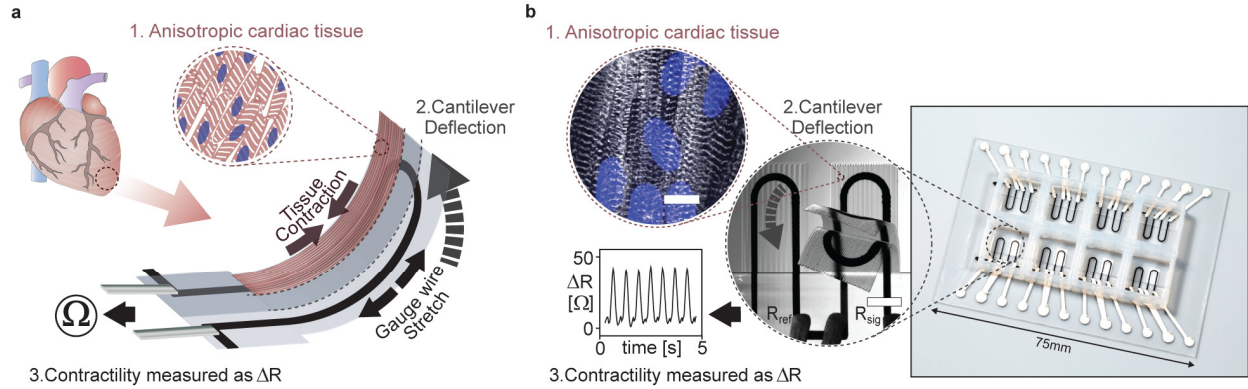
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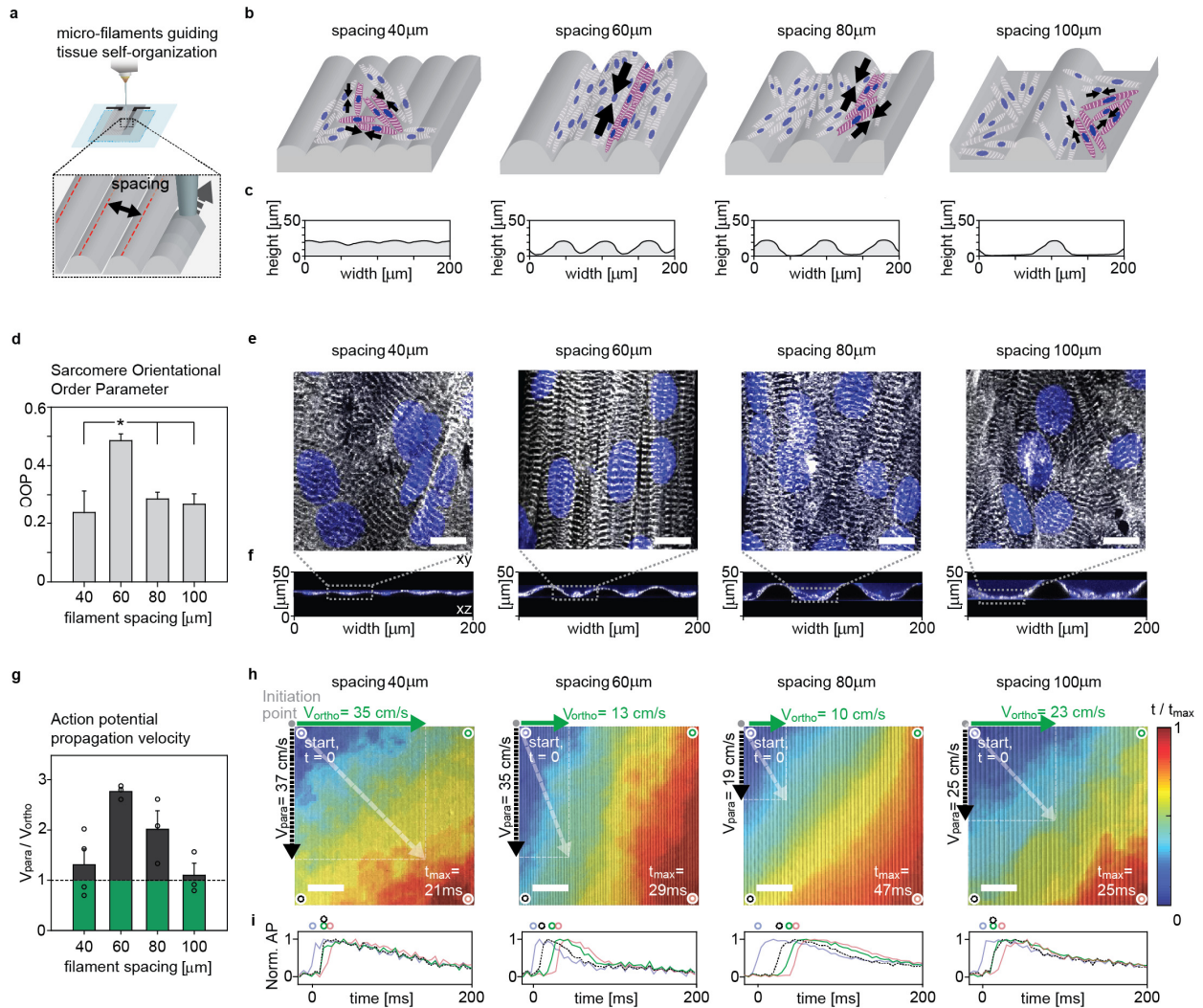
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2 **Figure 1 | Device principle and microscale 3D-printing procedure.** (a) Principle sketch of the
3 device. Contraction of an anisotropic engineered cardiac tissue (1) deflects a cantilever substrate
4 (2), thereby stretching a soft strain gauge embedded in the cantilever. This generates a resistance
5 change proportional to the contractile stress of the tissue (3). (b) The fully printed final device.
6 Insert 1: Confocal microscopy image of immuno-stained laminar NRVM cardiac tissue on the

1 cantilever surface. Blue: DAPI nuclei stain, White: α -actinin, scale bar 10 μ m. Insert 2: Still
2 images of a cantilever deflecting upon tissue contraction. Insert 3: Example resistance signal. **(c-**
3 **i)** Automated printing of the device on a 2" x 3" glass slide substrate in 7 sequential steps. For
4 each step, a corresponding still image from the printing procedure is displayed. For steps 1-5, a
5 stylus profiling cross-sectional contour of the cantilever is additionally displayed. **(c)** In print
6 step 1, a 0.5 μ m Dextran thin film sacrificial layer is printed **(d)** In print step 2, a 3 μ m TPU thin
7 film cantilever base is printed **(e)** In print step 3, a 6.5 μ m thick CB:TPU strain sensor loop is
8 added to cantilever base. **(f)** In print step 4, a 1.5 μ m TPU wire cover is added. **(g)** In print step 5,
9 20 μ m tall, 60 μ m wide PDMS micro-filaments are printed in slightly overlapping lines. The
10 filaments constitute the top part of the cantilever and guide cardiomyocytes to form anisotropic
11 laminar tissues. **(h)** In print step 6, electrical leads and contact are added using a high
12 conductivity Ag:PA ink **(i)** In print step 7, covers to insulate exposed wires and wells to contain
13 cells and media are printed using PDMS, PLA or ABS (See supplementary Fig S10).

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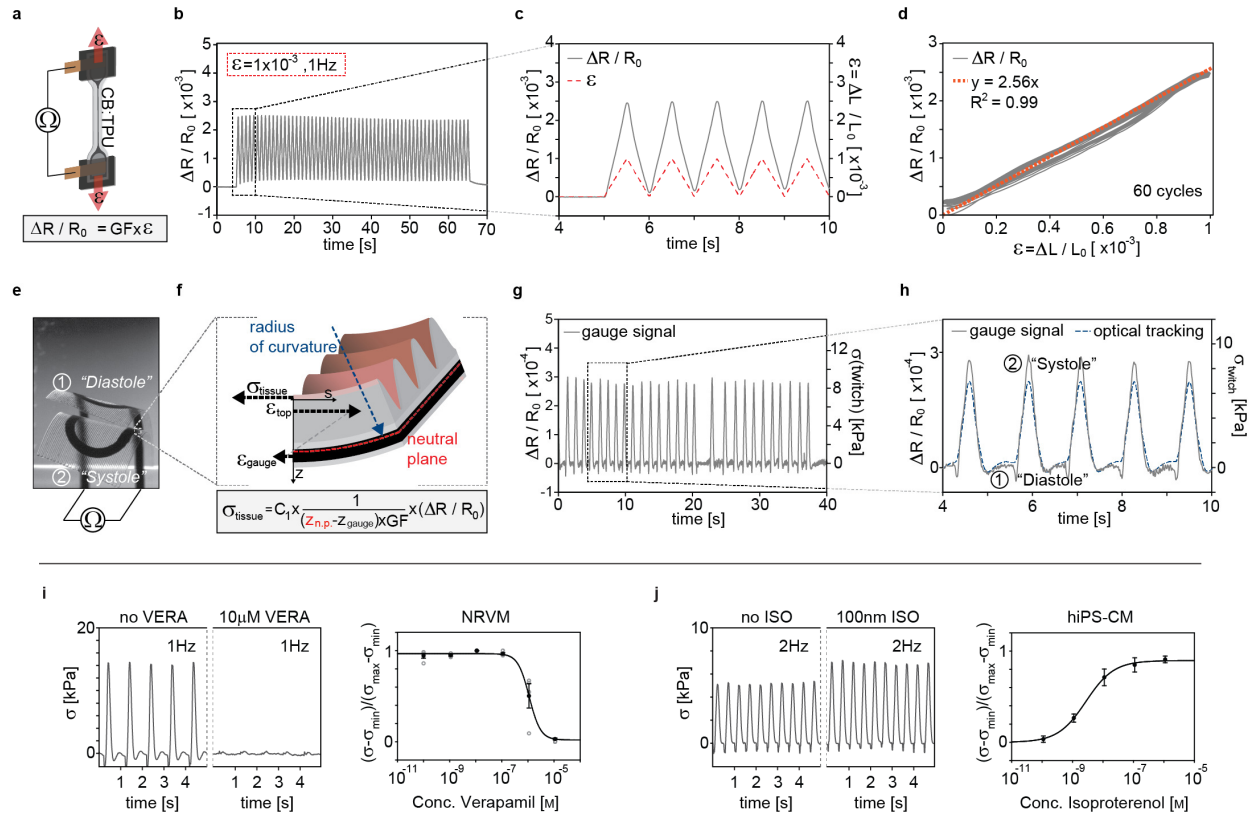


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2 **Figure 2 | Micro-grooves guide cardiomyocyte self-assembly into anisotropic engineered**
3 **tissues. (a)** Spacing of soft PDMS microfilaments **(b)** Sketch of micro-filaments guiding self-
4 assembly of engineered cardiac tissue. **(c)** Stylus profilometer contours of substrates with
5 filaments printed at 40, 60, 80 and 100 μm spacing **(d)** Sarcomere OOP of laminar NRVM tissues
6 developed on substrates with 40 (n=9), 60 (n=13), 80 (n=8) and 100 μm (n=10) filament spacing,
7 error bars are S.E.M. Significantly higher (*: P<0.05) degree of organization is observed for
8 60 μm spacing compared to all other conditions. **(e-f)** Representative confocal images from OOP
9 dataset, Blue: DAPI nuclei stain, White: α -actinin **(e)** x-y projection, scale-bars 10 μm **(f)** x-z line
10 scan. **(g)** Ratio between action potential (AP) propagation speed parallel and orthogonal to the

1 grooves for laminar NRVM tissue developed on substrates with 40, 60, 80 and 100 μ m filament
2 spacing, ($n \geq 3$). Individual data points included (circles), error bars are S.E.M. The propagation
3 speed of the action potential is faster in parallel than orthogonal to the grooves for all samples.
4 The anisotropy in propagation speed is larger for tissue developed on 60 μ m spaced filaments
5 than all other conditions. **(h)** Representative activation time maps for AP data set, overlaid wide
6 field microscope image of the samples as guide to the eye, scale-bars 0.8mm. Activation times
7 normalized to maximum observed activation (t_{max}), to account for tissue source variation. 2Hz
8 electrical point-stimulation is applied in top left corner of samples. Mean observed propagation
9 speed parallel (V_{para}) and orthogonal (V_{ortho}) to grooves is displayed as vectors. **(i)** Normalized
10 AP traces at four corners of activation map samples. Blue: at AP initiation corner, Red: At t_{max} -
11 corner, Black: Corner parallel to grooves, Green: Corner orthogonal to grooves.

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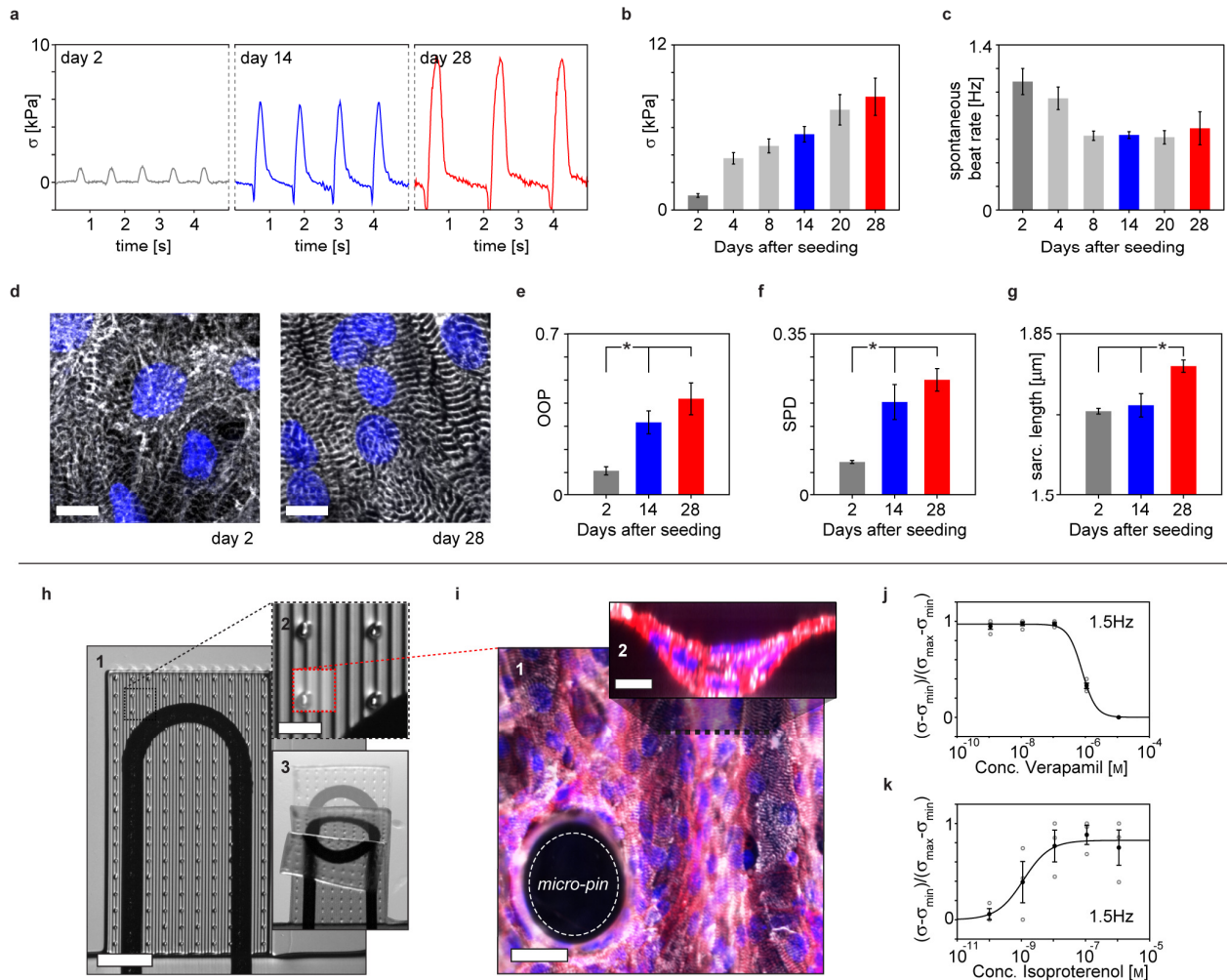
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2 **Figure 3 | CB:TPU gauge factor, sensor readout and example drug-dose studies.** (a) Sketch
3 of Instron test setup for determining CB:TPU gauge factor (GF). (b-d) Relative change in
4 CB:TPU resistance upon triangular cyclic straining to 0.1% at 1Hz. (c) Dark grey line: Observed
5 relative resistance change. Red dotted line: Strain applied. (d) Relative resistance change vs.
6 applied strain. Orange dotted line indicates linear fit to part of cycles with increasing strain
7 yielding a gauge factor of 2.56. (e) Wide-field microscope images of cantilever bending upon
8 tissue systole (2) and diastole (1) corresponding to systole (2). (f) Sketch of mechanical model applied to convert resistance
9 change to stress generated by the tissue, see Supplementary Inf. (g-h) Relative resistance
10 changes (left axis) and corresponding calculated tissue stress (right axis) recorded from
11 spontaneously beating cantilever. Blue dotted line in (h) indicates stress determined
12 independently by optical tracking of the cantilever radius of curvature. (i) Representative traces

1 of stress generated by a laminar NRVM tissue when tissue is exposed to verapamil and
2 corresponding dose-response curve (n=4), error bars are S.E.M, stress normalized between
3 maximal and minimal values, tissue paced at 1Hz, apparent EC_{50} $1.12 \times 10^{-6} M$. Individual data
4 points included (circles) **(j)** Representative traces of stress generated by a laminar hiPS-CM
5 tissue when exposed to isoproterenol and corresponding dose-response curve, (n=10), error bars
6 are S.E.M, stress normalized between maximal and minimal values, tissue paced at 2Hz,
7 apparent EC_{50} $2.74 \times 10^{-9} M$.

8



1
 2 **Figure 4 | Long term hiPS-CM contractile development and thicker laminar NRVM tissue**
 3 **devices** (a) Representative traces of contractile twitch stress generated by the laminar hiPS-CMs
 4 tissues at day 2, 14 and 28 (b-c) Contractile stress and spontaneous beat rate of hiPS-CMs tissues
 5 at day 2, 4, 8, 20 and 28 ($n \geq 10$) error bars are S.E.M. (d) Immuno-stained laminar hiPS-CMs
 6 tissues on device cantilevers at day 2 and day 28 after seeding, scale bars $10 \mu\text{m}$. Blue: DAPI
 7 nuclei stain White: α -actinin stain, Z-projection (e-g) SPD, OOP and sarcomere length of
 8 laminar hiPS-CM tissues at day 2, 14 and 28 ($n=5$) error bars are S.E.M., *: $P < 0.05$, (h) 1:
 9 Modified device cantilever containing micro-pin and micro-well to support thicker laminar
 10 NRVM tissue, 2: Detail of cantilever with micro-pins 3: Still images of a cantilever deflecting
 11 upon tissue contraction. (i) 1: Confocal microscopy Z-projection image of immuno-stained

1 thicker laminar tissue on the cantilever surface with micro-pin, scale bar 30 μ m. 2: Orthogonal
2 image of thicker laminar tissue in depth of grooves, scale bar 10 μ m, Blue: DAPI nuclei stain,
3 White: α -actinin, Red: actin. **(j)** Dose-response curve for verapamil, (n=4) for thicker laminar
4 NRVM tissue, error bars are S.E.M. Individual data points included (circles), tissue paced at
5 1.5Hz. Stress values assumed linear proportional to relative resistance change: $\sigma \sim \Delta R/R_0$ and
6 normalized between maximal and minimal values. Apparent EC_{50} $7.90 \times 10^{-7} M$ **(k)** Dose-response
7 curve for isoproterenol, for thicker laminar NRVM tissue, (n=3) error bars are S.E.M. Individual
8 data points included (circles), tissue paced at 1.5Hz. Thicker tissue stress values assumed linear
9 proportional to relative resistance change: $\sigma \sim \Delta R/R_0$. Stress normalized between maximal and
10 minimal values. Apparent EC_{50} $1.16 \times 10^{-9} M$

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