Estimating TMRCA, Modeling the Fixed Pedigree, and the Effect of the Y Chromosome on the Chromatin Landscape

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Estimating TMRCA,  
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the Effect of the Y Chromosome on the Chromatin Landscape

Abstract

This thesis consists of three chapters on different topics.

Chapter 1: We demonstrate the advantages of using information at many unlinked loci in order to better calibrate estimates of the time to the most recent common ancestor (TMRCA) at a given locus. To this end, we apply a simple empirical Bayes method to estimate the TMRCA. This method is both asymptotically optimal, in the sense that the estimator converges to the true value when the number of unlinked loci for which we have information is large, and has the advantage of not making any assumptions about demographic history. The algorithm works as follows: we first split the sample at each locus into inferred left and right clades in order to obtain many estimates of the TMRCA, which we can average to obtain an initial estimate of the TMRCA. We then use nucleotide sequence data from other unlinked loci to form an empirical distribution that we can use to improve this initial estimate.

Chapter 2: The population-scaled mutation rate $\theta$ is informative on the effective population size and is thus widely used in population genetics. We show that for two sequences, the Tajima’s estimator ($\hat{\theta}$), based on the average number of pairwise differences at $n$ unlinked loci, is not consistent and therefore its variance does not vanish even as $n \to \infty$. The non-zero variance of $\hat{\theta}$ results from the positive correlation between coalescence times that exists even at unlinked loci, due to the process of Mendelian percolation through a fixed pedigree. We derive this correlation under the discrete-time Wright-Fisher model (DTWF), and we point out the effects leading to this surprising result. In particular, whether loci were sampled from the same chromosome (even if
very far apart) or from different chromosomes affects the extent of this correlation. We also derive a lower bound on the correlation by conditioning on the fixed number of shared ancestors that connect the pedigrees of the two sequences. We finally obtain empirical estimates of the correlation of coalescence times under demographic models inspired by large-scale human genealogical data. Although the effect we describe is small (of order $1/N_e$, where $N_e$ is the effective population size), it is important to recognize this feature of statistical population genomics which runs counter to commonly held notions about unlinked loci.

Chapter 3: The *Drosophila melanogaster* Y chromosome is able to affect gene expression across the genome. It has been assumed that it does so by modifying the chromatin landscape. We screen two African and two European Y introgression lines for differential expression as well as differential binding in two proteins: Lamin and D1. There is significant intra-population variation in gene expression in the African population, which is surprising given the selective forces at play. Because that there are very few SNP differences in African populations, we can conclude that the effect of the Y chromosome is driven by other mutational events, like variation in repetitive regions. We find that differential binding does occur, and the strongest signals for differential binding are in regions of tandem repeats and centromeric regions. We can conclude from this that non-coding RNA likely plays a mediating role in influencing chromatin state, but also that a variety of different mechanisms are probably at play.
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Chapter 1

Empirical Bayes Estimation of Coalescence Times From Nucleotide Sequence Data

Leandra King, John Wakeley

1.1 Introduction

Without intra-locus recombination, all DNA sequences sampled at a given genetic locus originate from a common ancestor. That is, if we follow the genetic lineages of these sequences back in time, they will merge with one another until a single inheritance path remains. For each locus, this process yields a genealogical tree which unites all of the sampled sequences. The time until the most recent common ancestor (TMRCA) of a particular locus is the height of the genealogical tree at that locus.

TMRCA estimates are commonly used in inferring demographic history. For example, the TMRCA can be used to place an upper bound on the divergence time of subpopulations, if the migration rate between subpopulations and the size of each subpopulation is relatively small (Rosenberg and Feldman, 2002). This idea has been applied in order to obtain the evolutionary history of a number of different organisms, from chaffinches to anchovies (Griswold and Baker, 2002; Hailer...
Early papers in the TMRCA literature studied the human mtDNA ancestor, which supported the African origin hypothesis (Vigilant et al., 1991). Later studies sought to infer the TMRCA of the Y chromosome, in order to shed light on the origin and dispersal of modern humans. This is challenging due to the scarcity of DNA sequence polymorphisms on the Y chromosome (Hammer, 1995; Jakubiczka et al., 1989). One early study examined the Zfy intron, which was revealed to be completely monomorphic in a sample of 38 males (Dorit et al., 1995). Estimating the TMRCA of this intron necessitated a Bayesian approach, because any estimate proportional to the number of mutations would have given a value of zero. Dorit et al. (1995) used a uniform prior distribution on the TMRCA, which was considered inappropriate by a number of commenters, who advocated using priors that stemmed from coalescent theory and their preferred demographic models (Donnelly et al., 1996; Fu and Li, 1996; Weiss and von Haeseler, 1996). As a result of the lack of signal in the data, these different studies inferred very different estimates of the TMRCA (Brookfield, 1997). Further efforts to infer the TMRCA for other Y-chromosome data have also been affected by this dependence on the prior (Hammer, 1995; Whitfield et al., 1995; Walsh, 2001).

Given the interest in the TMRCA of an individual gene in inferring demography, the dependence of the estimate on the prior demographic model is particularly problematic (Brookfield, 1997). In contrast to parametric Bayesian methods such as those applied to Y-chromosome data, frequentist approaches such as maximum likelihood do not require the specification of a prior, and so might appear preferable. One such frequentist estimator is the one proposed by Tang et al. (2002). In this method, nucleotide sequence data are used to partition the sample into two groups, corresponding to the inferred two clades on either side of the root of the tree. Tang et al. (2002) then estimate the TMRCA using the average number of nucleotide sequence differences across all left-right clade pairs, $D_i$. Of course, application of this method to the Zfy data would give an estimate of zero for the TMRCA, which is a clear underprediction. More generally, if Tang et al. (2002) had regressed true TMRCA on estimated TMRCA, it would have been revealed that their method tends to underpredict when the number of segregating sites at a locus is small and to overpredict when it
is large. This is because an extreme number of segregating sites at a locus often results from a combination of a relatively small or large TMRCA at that locus and a relatively small or large number of mutations conditional on the TMRCA. Errors in inference will occur if all of the variation in the number of segregating sites is attributed to variation in times to most recent common ancestry, as is the case generally in frequentist approaches.

We propose augmenting the method of Tang et al. (2002) by using information at unlinked loci in order to better calibrate estimates of the TMRCA, and we introduce a very simple non-parametric empirical Bayes method. By “non-parametric”, we mean that we don’t assume that the prior on the TMRCA has any particular shape, only that all loci’s TMRCAs are sampled from the same distribution. In addition to improving on Tang et al.’s estimator, our method is advantageous over many Bayesian methods in that it makes no prior assumptions about the distribution of TMRCAs, and therefore can be used when the history of the population is completely unknown. We show that our method performs well in simulated data from a wide variety of demographic scenarios.

The idea of using information at additional loci to better the estimate at one locus appears in a number of recent methods, e.g. Li and Durbin (2011), Hobolth et al. (2007), though mostly with a spatial context along the genome that our method does not have. Similarly to Li and Durbin (2011), our method is able to extract information from a single genome, by making use of the number of heterozygote sites in sequences of DNA between recombination break points. We apply this method to a single Bantu individual and a single European individual, and are able to show that loci with the same number of heterozygous sites in different populations have different average TMRCAs.

1.2 Methods

1.2.1 Assumptions

We assume that the number of mutations at a locus follows a Poisson distribution with constant rate equal to the product of the total genealogical branch length and the per locus mutation rate.
In addition, we assume that each mutation generates a new segregating site, in accordance with
the infinite sites model as developed by Watterson (1975), which also includes the assumption
of complete linkage among sites at a locus. In fact, we allow for the possibility of within locus
recombination as long as it does not modify tree topology or TMRCA, which would preclude
the application of Tang et al. (2002)’s method. Finally, we assume that all of the different loci
under consideration are independent, in the sense that they represent independent samples from
the distribution of TMRCA. Approximate independence can be achieved by allowing for sufficient
inter-locus distance.

1.2.2 Simple existing methods for inferring the TMRCA of a sampled pair

Let us first consider estimating the TMRCA at a locus \( i \) in a sample of size 2. The number of
nucleotide differences \( x_i \) between these two samples follows a Poisson distribution with rate \( 2\mu_i\ell_i T_i \),
where \( \mu_i \) is the per nucleotide mutation rate at that locus, \( \ell_i \) is the length of the sequenced region,
and \( T_i \) is the time until coalescence measured in coalescent units. One natural estimator of \( T_i \) is
the maximum likelihood estimator, used for example by Tang et al. (2002):

\[
\hat{T}_{i,Freq} = \frac{D_i}{2\mu_i\ell_i}.
\] (1.1)

In Tang et al. (2002), \( D_i \) is the average number of segregating sites across all left-right clade pairs,
and for \( n = 2 \), \( D_i = x_i \).

Within the framework of coalescent theory, where priors for \( T_i \) have been derived for a number
of demographic models, it is more common to estimate \( T_i \) using a parametric Bayesian approach.
However, this requires certain assumptions about demographic history, which we might ideally
prefer not to make. One such estimator is the posterior mean, which can be obtained in the
manner of equations (19) and (20) in Tajima (1983) for an exponential prior on the TMRCA,
which corresponds to the demographic assumption of a constant population size:

\[
\hat{T}_{i,Bayes} = \frac{\theta}{(1 + \theta)} \frac{x_i + 1}{2\mu_i\ell_i},
\] (1.2)
where $\theta = 4N_e\mu_i\ell_i$, and $N_e$ is the effective population size.

1.2.3 Non-parametric Empirical Bayes approach (NPEB)

We can use Robbins (1955) method to improve on these simple frequentist and parametric Bayesian approaches, by utilizing information from other unlinked loci in the sample. Robbins considered the following case of sampling from a mixed distribution. Let $x_i$, conditional on some variable $T_i$, be specified by a Poisson distribution,

$$P(x_i|T_i) = \frac{T_i^{x_i}e^{-T_i}}{x_i!}.$$  

The $T_i$ are in turn independent and identically distributed according to some distribution, which we do not know and which we do not need to specify. For an illustration of the data generating process, see figure 1.1.

This data-generating process exactly describes the process that yields the number of mutations at unlinked loci in a genome, given our assumptions. That is, conditional on $T_i$ and $\mu_i\ell_i$, each $X_i$ is an independently distributed Poisson random variable with rate $2\mu_i\ell_iT_i$, and each $T_i$ is drawn i.i.d from an unknown distribution. For the sake of computational simplicity, we will assume that $2\mu_i\ell_i = 1$, which is equivalent to a simple rescaling of $T_i$.

![Figure 1.1: Data Generating Process for Robbins’ method](image)

Figure 1.1: **Data Generating Process for Robbins’ method**, in which the distribution $P(T_i)$ is unknown and does not need to be specified.

Under this compound sampling scheme (though initially not applied to genetic data), Robbins (1955) showed that we can obtain a point estimate of $T_i$ by making use of Bayes’ rule and the form
of the Poisson probability distribution:

\[
E[T_i|X_i = x_i] = \int T_i P(T_i|x_i) dT_i = \int T_i \frac{P(x_i|T_i)P(T_i)}{P(x_i)} dT_i
\]

\[
= \frac{(x_i + 1)}{P(x_i)} \int \frac{e^{-T_i}T_i^{x_i+1}}{(x_i + 1)!} P(T_i) dT_i
\]

\[
= \frac{(x_i + 1)}{P(x_i)} \int P(x_i + 1|T_i)P(T_i) dT_i
\]

\[
= \frac{(x_i + 1)P(x_i + 1)}{P(x_i)},
\]

where \(P(x_i)\) is the marginal probability that \(X_i = x_i\), that is, the marginal probability that we observed exactly \(x_i\) segregating sites at locus \(i\). As can be seen from the sampling structure depicted in Figure 1, this marginal distribution, which we could simply call \(P(x)\), does not depend on \(i\).

When the number of loci is not too small, we can approximate \(P(x_i)\) by the fraction of loci where the number of observed segregating sites is equal to \(x_i\). We use \(m_{x_i}\) to refer to \(m\) times this fraction, or the number of loci with exactly \(x_i\) mutations. In this way we obtain the following estimator of the TMRCA at locus \(i\):

\[
\hat{T}_{i,NPEB} = (x_i + 1)\frac{m_{x_i+1}}{m_{x_i}}.
\]

As a note, mutation rates vary across the genome, and we are not assuming a single underlying mutation rate. Loci with relatively high mutation rates for example can be truncated, such that the product of the mutation rate and the locus length \(\mu_i\ell_i\) across all considered loci is roughly similar.

Robbins (1955) proved that this estimator is asymptotically optimal. That is, as as the total number of loci sampled grows \((m \to \infty)\), its Bayes risk (such as the mean squared error) converges to the Bayes risk for the Bayesian model where the true prior of the \(T_i\), and therefore \(P(x_i)\), is known. As might be expected, Robbins’ method behaves erratically in cases where there are few data. If for example \(m_{x_i+1} = 0\), that is if no loci have exactly \(x_i + 1\) segregating sites, then our estimate of \(T_i\) corresponding to a locus \(i\) where there are \(x_i > 0\) segregating sites would be 0, which is clearly wrong. In order to mitigate this effect, there are a number of smoothing techniques one
might apply (Gale and Church 1990, 1994; Lidstone 1920; Good 1953). In this paper, we will only attempt to estimate $T_i$ using Robbins’ method when loci where there are $x_i$ segregating sites and loci where there are $x_i + 1$ segregating sites are not rare. It is indeed for these loci that Robbins’ method shows a clear advantage over traditional methods that do not incorporate information from other independent loci.

Another consequence of variation in $m_{x_i}$ is that estimates of $T_i$ are not necessarily a non-decreasing function of the number of mutations $x_i$. In fact we would expect loci in which there are more mutations to be at least as ancient as loci in which there are only a few. In order to remedy this, we can fit a weighted isotonic regression of the inferred mean $\hat{T}_{i,NPEB}$ on the number of mutations using the pava() function in the “Iso” package (Turner 2015) in R (R Core Team 2015), where we weight each value by 

$$\frac{(x_i + 1)^2 m_{x_i+1}^2}{m_{x_i}^2 \left( \frac{1}{m_{x_i}} + \frac{1}{m_{x_i+1}} \right)},$$

and obtain a new set of estimators, denoted by $\hat{T}_{i,NPEB}^{W}$. We use these weights as an approximation of the variance of $\hat{T}_{i,NPEB}$, as will be explained in the section entitled “Effectiveness of Robbins’ method”. As the isotonic regression yields the least squares best fit among nondecreasing relationships, performing this step ensures that $\hat{T}_i \leq \hat{T}_j$ if there are fewer mutations at locus $i$ than at locus $j$.

To summarize, Robbins’ method uses the ratio of the number of loci with exactly $x_i$ and $x_i + 1$ mutations in order to calibrate the TMRCA at a given locus with exactly $x_i$ mutations. We then incorporate the knowledge that the expected number of segregating sites at a locus is a non-decreasing function of its TMRCA, by running an isotonic regression on the TMRCA estimates.

1.2.4 Generalizing our estimator to a sample of size $n \geq 2$

In generalizing our estimator for use on samples of size $n \geq 2$, we are inspired by the frequentist estimation of coalescence times from nucleotide sequence data using a tree-based partition in Tang et al. (2002). In that work, the $n$ sequences are first partitioned into two subsets which are meant to correspond to the left and right clades of the genealogical tree. The MRCA of any two sequences,
one in the left clade and one in the right clade, is the root of the tree. Tang et al. (2002) propose an estimator of the TMRCA based on the average number of pairwise differences $D_i$ between sequences in the left clade and sequences in the right clade (see equation 1.1).

Although genealogical trees are not always completely resolved by the data, in many cases there is little ambiguity about the branching pattern at the root (Tang et al. 2002). When ambiguity does exist at the root, Tang et al propose a partition algorithm that is less biased than forcing the pair of sequences that differ most from each other to be in different clades. This algorithm does not require knowledge of the ancestral state at the segregating sites. The 8 steps of this algorithm are described in detail in Tang et al. (2002).

We use the following steps to infer $T_i$ in cases where $n > 2$, which we also illustrate in figure 1.2.

1. For each locus $i$, where $1 \leq i \leq m$, we use Tang et al’s tree partitioning algorithm to partition the sample at locus $i$ into left and right clades.

2. From the set of left-clade samples, we pick at random a single sample. We also pick at random a sample from the set of right-clade samples. We calculate the number of pairwise differences and repeat this process for every locus $i$. The reason we count the number of differences between single pairs of left-right clade sequences instead of averaging the number of differences across all left-right clade pairs is that Robbins’ method requires $x_i$ to be an integer. We then calculate a $\hat{T}_{i,NPEB}$ for each locus using these counts at all $m$ loci, according to equation 1.3. The result of this step is a table which contains estimates of TMRCA corresponding to different observed numbers of segregating sites. We then fit a weighted isotonic regression to these estimates, where each estimate is weighted according to formula 1.4.

3. Clearly, at the end of the previous step, we have not used much of the information from our sample, as we have sampled only one left-clade right-clade pair from each locus. We therefore repeat the previous step over all possible left-right clade pairs at a particular locus, which all have same TMRCA if the partitioning algorithm is correct. For each locus, the number of possible left-right clade pairs depends on the topology of the tree at that locus. If a single
sequence forms one of the clades, the data at that locus will consist of \( n - 1 \) highly correlated pairwise differences. When the tree is balanced, there are \( (n + 1(n \text{ is odd}))(n - 1(n \text{ is odd}))/4 \) pairs, many more than in the unbalanced case. We repeat step 2 until all left-right clade pairs have been used at least once. For loci with the maximum observed number of pairs, each pair is used exactly once. For loci with fewer pairs, some pairs are used multiple times; these are sampled uniformly at random after all pairs at a locus have been used once. At the end of this step, we obtain between \( n - 1 \) and \( (n + 1(n \text{ is odd}))(n - 1(n \text{ is odd}))/4 \) tables, depending on the \( m \) inferred tree configurations. That is, the number of tables produced is equal to the number of pairs in the locus with the largest amount of left-right pairs.

4. We average the entries in all of the tables obtained in the previous two steps, i.e. the estimates of TMRCA for each observed number of segregating sites at a locus, and in this way we obtain a final table with the aggregate information that links each integer-valued unique number of segregating sites to a unique estimate of the TMRCA.

5. We then consider the data at a single locus \( i \). We calculate \( D_i \), the average number of segregating sites over all left-right clade pairs at this locus. If this average is an integer, then the estimate of the TMRCA can be read from the row corresponding to value \( D_i \) in the final table. More likely than not, though, \( D_i \) is not an integer. We can create a piecewise linear function that extends our estimates of the TMRCA to non-integer values of \( D_i \). Our estimate of the TMRCA is then a weighted average of the estimates of the TMRCA in the rows corresponding to \( \lfloor D_i \rfloor \) and \( \lceil D_i \rceil \).

We note here that the presence of recombination does not compromise the method in any way when \( n = 2 \) but does require a reinterpretation of the meaning of the results. The NPEB estimate will no longer correspond to a single TMRCA at a given locus but to an average TMRCA across the locus. This is due to the additive properties of the Poisson distribution and to the fact that, in a sample of size 2, intra-locus recombination will not produce a new tree with a different shape. Indeed, in a sample of size 2, there is no ambiguity concerning the members of the left and the right clades. For a sample size greater than 2, we require no intra-locus recombination that affects
Figure 1.2: Inferring $T_i$ for $n \geq 2$. Here we illustrate the particular case where $n = 4$ and $m = 3$. Step 1 and 2 focus on the left-most column. In step 1, we partition each locus into left and right clades, based on Tang’s algorithm. Left clades lineages are depicted in red, and right clade lineages are depicted in black. In step 2, we consider a single random left clade member and a single random right clade member at each locus. We represent these with bold lines, and count the number of pairwise differences (mutations are represented by black dots), which we write below each tree. In our example, the number of pairwise differences at each locus is (3,0,4). We use this information to calculate an estimate of $T_i$ for each unique number of segregating sites, which we store in table 1. In step 3, we repeat this for all left-right pairs. As there are four left-right clade pairs at locus 2, we resample an extra left-clade right-clade pair at loci 1 and 3, which corresponds to the 4th column. In step 4, we average the TMRCA estimates in all four tables to obtain a final table, again linking different numbers of segregating sites to different estimates of TMRCA. Finally, in step 5, we calculate the average number of pairwise differences between inferred left and right clades at each locus. In our case, this is $(D_1, D_2, D_3) = (3, .5, 3.67)$. The estimate at locus 3 for example will be .67 times the estimate at a locus with 4 mutations and .33 times the estimate at a locus with 3 mutations.
tree shape, because otherwise we could not partition our sample into left and right clades.

1.3 Results

1.3.1 Effectiveness of Robbins’ method

In order to assess where Robbins’ NPEB method is most effective, we calculate the variance of \( \hat{T}_{i,NPEB} \) as a function of \( m, m_x, \) and \( m_{x+1} \). Using a Taylor expansion, we can approximate the variance of the ratio of two random variables (Rice, 2007):

\[
\operatorname{Var} \left( \frac{m_{x+1}}{m_x} \right) \approx \left( \frac{\operatorname{E}(m_{x+1})}{\operatorname{E}(m_x)} \right)^2 \left( \frac{\operatorname{Var}(m_{x+1})}{\operatorname{E}(m_{x+1})^2} - 2 \frac{\operatorname{Cov}(m_x, m_{x+1})}{\operatorname{E}(m_x) \operatorname{E}(m_{x+1})} + \frac{\operatorname{Var}(m_x)}{\operatorname{E}(m_x)^2} \right). \tag{1.5}
\]

We can represent the distribution of the \( m_{xi} \) for each observed \( x_i \) by a multinomial distribution, as long as we create a bin to account for all unobserved yet possible values of \( x_i \). In the model there are countably infinite possible numbers of segregating sites, but in practice the number is limited by \( \ell_i \) the length in nucleotides of each locus \( i \). By the properties of the multinomial, we have \( \operatorname{E}(m_{xi}) = mP(x_i), \operatorname{Var}(m_{xi}) = mP(x_i)(1-P(x_i)) \) and \( \operatorname{Cov}(m_{xi}, m_{xi+1}) = -mP(x_i)P(x_i+1) \).

Equation (1.5) then simplifies to:

\[
\operatorname{Var} \left( \frac{m_{x+1}}{m_x} \right) \approx \frac{P(x_i+1)^2}{mP(x_i)^2} \left( \frac{1}{P(x_i)} + \frac{1}{P(x_i+1)} \right) .
\]

Therefore, as \( \hat{T}_{i,NPEB} = (x_i + 1) \frac{m_{x+1}}{m_x} \), we have:

\[
\operatorname{Var} (\hat{T}_{i,NPEB}) = \operatorname{Var} \left( (x_i + 1) \frac{m_{x+1}}{m_x} \right) \approx (x_i + 1)^2 \frac{P(x_i+1)^2}{mP(x_i)^2} \left( \frac{1}{P(x_i+1)} + \frac{1}{P(x_i)} \right) . \tag{1.6}
\]

To illustrate where Robbins’ method is most effective, we apply (1.6) to each value \( x_i \) of an example distribution illustrated in figure 1.3. As one might expect, if we increase \( m \), we get more accurate results over more points. For moderate numbers of loci \( m \), results are still very accurate.
if $P(x_i)$ is not too small, especially in comparison with $P(x_i + 1)$. Finally, the contribution of the first term on the right side of (1.6) is smallest when $x_i$ is small. For these reasons, our method can give accurate results at sites with $x_i = 0$ segregating sites.

Using the observed data, we can approximate the variance at each point by assuming $m_{x_i} \approx mP(x_i)$. This is how we obtain the weights for our isotonic regression (see 1.4).

![Figure 1.3: Accuracy of Robbins’ method.](image)

For each value of $x_i$, $mP(x_i)$ is the expected number of sites with exactly $x_i$ segregating sites. The bars are shaded and labeled according to the approximate standard deviation of $\hat{T}_{i,NPEB}$ at each locus with $x_i$ mutations, obtained using equation (1.6). There is no estimate of the TMRCA for the locus with 7 mutations, because the NPEB method would require the existence of some number of sites with exactly 8 mutations, and this is not the case here.

### 1.3.2 Simulation results in a wide range of population histories

In order to test the performance of our estimator against the traditional frequentist and parametric Bayesian estimators, we run a series of simulations. Programs sufficient to reproduce all of the results we present are available at https://wakeleylab.oeb.harvard.edu/resources.
We generate synthetic data using the program MSMS (Ewing and Hermisson, 2010), which generates sequence data and TMRCA values under a range of demographic scenarios including population growth, subdivision, and admixture. We vary the population mutation rate \( \theta \), the exponential growth rate of the population \( g \), the number of sequences from which we build our genealogies \( n \), and the divergence time between populations \( d \) across a range of parameters described in table 1.1. We use a cutoff of .2 in step 6 of Tang et al. (2002)'s tree partitioning algorithm. This essentially disallows sampled pairs that have relatively very few nucleotide differences from being selected to belong to different tree clades. We choose this value as it is the default setting in Tang et al. (2002). Note again that we measure time in units scaled by the population mutation rate \( \theta \).

We illustrate the performance of the method for two sample sizes, \( n = 2 \) and \( n = 8 \). Felsenstein (2006) suggested \( n = 8 \) as an optimal choice to balance accuracy of estimating \( \theta \) against the costs of genotyping. To justify \( n = 8 \), we might also appeal to the results that the expected TMRCA is equal to \( 2(1 - 1/n) \) and that the probability the MRCA of the sample contains the MRCA of the entire population at a locus is equal to \( (n - 1)/(n + 1) \) (Saunders et al., 1984) if the interest is in the whole-population TMRCA at each locus. Concretely, this means that the TMRCA for 8 lineages is likely to be close to the TMRCA for many more lineages.

For each demographic scenario, we simulate \( m \) independent genealogies. We then use our algorithm to calculate \( \hat{T}^W_{i,NPEB} \) at each locus \( i \). To measure performance, we first compute the mean squared error (MSE) of our estimators at all loci for which our estimate of the variance of \( \hat{T}^W_{i,NPEB} \) is smaller than some threshold, chosen to be 0.1 in these simulations. We will assume that there are \( m^* \) such loci:

\[
\text{MSE}_s \left( \hat{T}^W_{i,NPEB} \right) \approx \frac{1}{m^*} \sum_{\text{Var} \hat{T}^W_{i,NPEB} < 0.1} \left( \hat{T}^W_{i,NPEB} - T_{i,\text{True}} \right)^2,
\]

where \( T_{i,\text{True}} \) is the true TMRCA at locus \( i \) given by MSMS. The subscript \( s \) is the index of one simulated set of \( m \) loci under a given demographic scenario. In order to have a more accurate estimate of our error, we repeat these simulations \( S \) different times for each combination of parameters. We then average MSE\(_s\) over the \( S \) different sets in order to obtain the final measure of the
accuracy of our estimator, given the demographic scenario.

We impose a cutoff variance because we only expect our method to be advantageous when the variance of the estimator is reasonably small. That is, it is only beneficial in estimating the TMRCA of a locus \( i \) where \( m_{x_i} \) and \( m_{x_{i+1}} \) are large. Reasonable values of this threshold will depend on the population mutation rate \( \theta \). The smaller the cutoff variance, the smaller \( m^* \), the number of loci for we estimate a TMRCA. We specifically chose .1 in these simulations to restrict ourselves to loci whose TMRCA we could accurately predict, at least more accurately than using Tang et al. (2002)'s method across the range of parameters in our simulations.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Values</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of independent sites</td>
<td>( m ) 250, 500, 1000, 2000, 4000</td>
</tr>
<tr>
<td>Population mutation rate</td>
<td>( \theta ) 0.25, 0.5, 0.75, 1, 2</td>
</tr>
<tr>
<td>Growth rate ( g )</td>
<td>0, 0.5, 1, 2</td>
</tr>
<tr>
<td>Divergence time ( d )</td>
<td>0, 1, 3</td>
</tr>
<tr>
<td>Sample size ( n )</td>
<td>2, 8</td>
</tr>
</tbody>
</table>

Table 1.1: Parameter values in simulations

1.3.3 Comparison to Tang’s method and the parametric Bayes posterior mean

Figure 1.4 is a scatterplot of the MSE of estimates using the method of Tang et al to those obtained using NPEB for simulations over the parameters in the multi-dimensional grid described in 1.1. We see that Robbins’ method always performs better than Tang et al.’s approach as measured by MSE.

As we increase \( m \), our estimates become more and more accurate: the NPEB MSE converges to the Bayes MSE where the true prior is assumed (Robbins 1955). We illustrate this for \( g = 0, d = 0, n = 2 \) and \(.25 < \theta < 2.0 \) in figure 1.5. The parametric Bayes estimates were obtained by assuming (correctly) that the values \( T_i \) were drawn from an exponential distribution with parameter \( \theta \). We update the prior on \( T_i \) with the observed number of mutations \( x_i \), and in this way obtain the posterior on \( T_i \). We then report the mean of this posterior (see equation 1.2). For \( m = 250 \), the MSE of the NPEB estimator is, depending on \( \theta \), about 3.5 to 7.4 percent higher than the MSE of the Bayesian estimator using the correct prior. For \( m = 4000 \), the difference is even smaller, with
Figure 1.4: Accuracy of NPEB method vs Tang et al. The NPEB method performs better than Tang et al.’s method in terms of MSE across the range of parameters in the multidimensional grid described in Table 1.1. Different values of $\theta$ are plotted using different shapes, and different values of $m$ are plotted using different colors (large values are in red). In dashed we plot the $y = x$ line.

an increase of only about 1.2 percent.

We found that when the assumed prior is not true, Robbins estimator performs better than the parametric Bayesian estimator as long as $m$ is big enough and the assumed prior is different enough from the true prior (Robbins, 1955). We illustrate this in a particular case, for different values of $g > 0$, when the prior assumes $g = 0$, and for demographic parameter values $d = 0$ and $\theta = .5$ in Figure 1.6. It is worth noting that as we increase $m$, we also increase the number of loci $m^*$ for which we are estimating the TMRCA. For this reason, the raw MSEs (e.g. Fig. 1.4) are not completely comparable across different values of $m$, as they depend on this value $m^*$ (see Eq. 1.7).

In summary, our method performs better than Tang’s method across the entire range of tested parameters. Unsurprisingly, the parametric Bayesian estimator performs better than the empir-
Figure 1.5: **NPEB vs Bayes with true prior assumed.** We plot \((MSE_{NPEB} - MSE_{Bayes})/MSE_{Bayes}\) for different values of \(m\), which we vary in color, and different values of \(\theta\), which we vary in shape. For the parametric Bayes case, we assume as a true prior a constant population size and a divergence time of 0. We use a sample size of 2.
ical Bayes estimator when the true prior is assumed. However, our method can outperform the parametric Bayesian estimate in terms of MSE when the assumed prior is incorrect.

Figure 1.6: **NPEB vs Bayes with wrong prior assumed.** Here we assume as a prior a constant population size, but in reality the exponential growth rate varies between 0 and 2 (see x-axis). The value of $\theta$ is 0.5, and the sample size is 2. Values of $m$ range from 250 (in gray) to 4000 (in red).

## 1.3.4 Admixture case study

We also consider the special case of admixture, as a more complicated demographic history. In this case, we can still assume that the true TMRCAs are independent and identically distributed, but this time according to a more complicated distribution that exhibits bimodality (see figure 1.7). Using again the program MSMS ([Ewing and Hermisson 2010](#)), we simulate the genealogies of pairs of just admixed individuals. Their parent populations diverged 6 time units in the past, with 50 percent of the genetic material in the sample originating from the first population and 50 percent from the second population. This means that 50 percent of sampled lineages will not be able to
coalesce before 6 time units in the past. We fix \( \theta = 1 \), and consider \( m = 8000 \) independently segregating loci. Histograms of the true MRCAs and the number of mutations per site are shown in figure 1.7, the latter being equal to Tang’s estimator in this case (\( \theta = 1 \)). We can see that there is considerable bimodality in the TMRCAs, which translates to bimodality in the number of mutations at different loci.

Figure 1.7: **Histograms of true and inferred TMRCAs in the admixture model.** We can see that the number of mutations follows a similar distribution as the true times, but with higher variance. [Tang et al. (2002)](#)’s estimate of the TMRCA is proportional to the number of mutations.

Plotting the true TMRCAs versus the inferred TMRCAs using the two methods reveals that the true TMRCAs are appropriately shrunk using our method, and that Tang’s method especially overestimates the TMRCAs in cases where there are a lot of mutations, and underestimates them in cases where there are very few mutations (see Figure 1.8). We used .2 as a cutoff value, such
that any points with variance greater than .2 are not displayed. Note that this figure represents a single (though typical) run of the algorithm. How well the NPEB ends up approximating the true TMRCA depends somewhat on the stochasticity of the data.

Figure 1.8: **Comparison of different methods in admixture model.** In black circles is a scatterplot of the number of mutations at a locus and the true TMRCA at that locus. The red dots represent the average TMRCA for each locus with a given number of mutations. Values on the red diagonal line for each number of mutations represent estimates of the TMRCA using Tang’s method, which tends to overestimate the value of the TMRCA when there are a large number of mutations, and underestimate it when there are a small number of mutations. The white crosses represents NPEB estimates of the TMRCA for loci with 0 to 7 mutations. We do not report NPEB estimates of the TMRCA above 7 mutations because the variance of the estimate is greater than our cutoff value, .2.
1.3.5 Analysis of TMRCAs from human genomes

We also apply our method to data from 37,574 neutrally evolving autosomal loci from a European and a Bantu individual (Gronau et al., 2011). Each inter-locus distance is at minimum 50,000 base pairs, a distance deemed sufficiently high by Gronau et al. (2011) that the genealogies can be assumed to be approximately uncorrelated. These presumably neutral loci are 1,000 base pairs in length, and were chosen to avoid recombination hot-spots. We remove any masked bases, and reduce all of our loci to 900 base pairs, by truncating loci with greater than 900 unmasked bases and removing loci with less than 900 unmasked base pairs. We use Gronau et al. (2011)'s estimate of the mutation rate of $0.7 \times 10^{-9}$ mutations per site per year and for the sake of illustration assume no variation in mutation rate across these loci, which we would otherwise control for by varying the length of each locus. Because of diploidy, we have a sample of size 2 for each individual.

The distribution of numbers of mutations (or heterozygous sites) is different in the case of the Bantu and the European (see figure 1.9), which we might attribute to the well-known bottleneck in the ancestry of European populations (Keinan et al., 2007; Voight et al., 2005). In particular, the average number of pairwise differences is greater for Bantu than for European. In figure 1.10 we plot the inferred TMRCA at each locus for each of these two genomes. We notice that, unlike with our method, the TMRCAs estimated using Tang’s method do not vary depending on the population. Using our method to estimate TMRCAs, we find that the calibration is less intense for the European sample than it is for the Bantu sample, which makes sense in light of the fact that the frequency of sites with exactly $x_i$ mutations decreases more sharply as $x_i$ increases for the European sample (figure 1.9).

1.4 Discussion

We have shown that the problem of estimating the TMRCA of a sample can be framed in such a way that it allows for the use of NPEB methods, such as a modified Robbins’ method. The advantage of these methods is that they use data from all loci to efficiently account for the randomness of mutation, through which loci with the same TMRCA can have very different numbers of segregating
Figure 1.9: Frequency histogram of the number of heterozygote sites in a Bantu and a European individual.
Figure 1.10: Estimated TMRCA at loci with different numbers of mutations. We compare the NPEB method and Tang’s method in estimating the TMRCA of different loci in a Bantu individual and a European individual. Tang’s method does not depend on the distribution of the number of mutations in the population. We do not report NPEB estimates of the TMRCA above 4 mutations because their approximated variance is greater than our cutoff value.
sites. In all of our simulations, Robbins’ method, one of the simplest NPEB methods, showed radical improvement over Tang et al’s maximum likelihood method (this is because the method makes use of a lot more of the available information). It also performed very well against a parametric Bayesian method in which it is assumed that the true prior for TMRCA is known.

It is particularly useful in that Robbins’ method provides reliable estimates of the TMRCA even when the mutation rate is very low. Many of the nucleotide sequences we simulated had 0 segregating sites. Our method was nonetheless reliably able to infer TMRCA at these loci, as long as there was enough information from other independently segregating loci. The other benefit of our method is that it does not require any prior assumptions on demographic history. We ran simulations using simple models of population expansion and divergence and showed that our method is effective in a wide variety of demographic scenarios.

For all cases where the genealogies uniting the sampled sequences are known, as for example when the sample is of size 2, the NPEB estimate may be calculated simply and directly using equation [1.3]. However, this method is somewhat limited to loci with sufficiently common numbers of segregating sites. It does not perform well with outliers, i.e. when $m_{x_i}$ is small.

More effective yet complicated NPEB approaches involve estimating the distribution $\hat{G}$ of the $T_i$ from the data. Laird (1978) proved that the distribution of $T_i$ that maximizes the likelihood of the data is a discrete distribution over finitely many points $j$. An estimate of this distribution can be obtained using the Expectation-Maximization algorithm (Dempster et al., 1977). We can then get estimates of each individual $T_i$ by using Bayes rule with $\hat{G}$ as a prior:

$$
E[T_i|X_i = x_i] = \frac{\sum_j T(j)P(x_i|T(j))\hat{G}(T(j))}{\sum_j P(x_i|T(j))\hat{G}(T(j))}.
$$

(1.8)

This approach is superior to Robbins’ method in that conditions of monotonicity and convexity are satisfied, and its success does not depend on the use of a squared error loss function over a general loss function (Carlin and Louis, 2000). However, it involves much more computation than Robbins’ method. In this paper, we concentrated on Robbins’ method as our goal was to show that there is information at independent loci, and that even the simplest NPEB method performs quite well, especially compared to the maximum likelihood approach.
Acknowledgments

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Chapter 2

A non-zero variance of Tajima’s estimator for two sequences even for infinitely many unlinked loci

Leandra King, John Wakeley, Shai Carmi

2.1 Introduction

The population mutation rate $\theta$ is defined as $4N_e\mu$, where $N_e$ is the effective population size and $\mu$ is the per locus per generation mutation rate. Two classic estimators were developed for $\theta$, Watterson’s (based on the number of segregating sites (Watterson 1975)) and Tajima’s (based on the average number of pairwise differences (Tajima 1983, 1989)). For a single pair of sequences, both estimators are identical (denoted here as $\hat{\theta}$) and equal to the number of differences between the sequences.

Increasing the number of sampled individuals has limited ability to improve these estimates of $\theta$, because shared ancestry reduces the number of independent branches where mutations can arise (Rosenberg and Nordborg 2002). Felsenstein (2006) showed that the variance of maximum likelihood estimates of $\theta$ decreases approximately logarithmically with the number of individuals sampled. In contrast, the variance decreases inversely with the number of independent loci. Thus,
to increase the accuracy of estimates of $\theta$, it is more effective to increase the number of independent loci than the sample size at each locus.

Naively, we might consider a set of $n$ unlinked loci, in the sense that they are separated by an effectively infinitely large recombination rate, to be independent. These loci may be sampled from the same or different chromosomes. We show here that as $n \to \infty$, the variance of the resulting estimate of $\theta$ does not converge to zero. This behavior results from the fact that coalescence times, even at unlinked loci, are in fact not independent, but rather weakly correlated. This correlation is due to Mendelian percolation through the fixed underlying pedigree which is shared by all loci (Wakeley et al., 2012). In other words, gene genealogies at different loci are constrained by having to traverse the same common family tree.

The extent of the correlation of coalescence times depends on the sampling configuration, i.e., whether the sampled loci are located on the same chromosome, on different homologous chromosomes, or on non-homologous chromosomes. This is because the correlation of coalescent times is induced in part through linkage in the first few generations. In particular, loci sampled from a same chromosome must have been inherited from the same parent, and loci sampled on different homologous chromosomes must have originated from different parents. We derive the correlation analytically using a diploid discrete time Wright-Fisher model (DDTWF), which is an extension of the haploid DTWF model previously advocated by Bhaskar et al. (2014) for the study of large samples from finite populations, in which multiple-merger coalescent events might occur.

While the results of the DDTWF model are exact, the dependence on the pedigree is implicit. For the case of non-homologous chromosomes, we derive an explicit lower bound on the variance of coalescence times, by taking into account the sharing of genealogical common ancestors across loci. This calculation, which expands on previous work (Wakeley et al., 2012), provides insight on how the shape of the gene genealogies is constrained by the underlying pedigree, and on the effect of these constraints on estimates of the effective population size.

Our results for the variance of $\hat{\theta}$ were obtained under the Wright-Fisher demographic model. To shed light on the variance of $\hat{\theta}$ under more realistic demographic models, we run simulations based on real, large-scale human genealogical data (Erlich, 2015). The pedigrees inspired by different
human populations differ from each other and from the Wright Fisher pedigrees in a number of ways, for example in the variance of the relatedness of any two randomly chosen individuals. These differences lead to differences in the variance of $\hat{\theta}$ for each population, even if they have the same effective population size.

### 2.2 The relation of the variance of $\hat{\theta}$ to the correlation of the coalescence times

For a sample of size two at $n$ loci, the estimator of $\theta$ can be expressed as

$$\hat{\theta}_{(n)} = \frac{1}{n} \sum_{i=1}^{n} \hat{\theta}_i,$$

where $\hat{\theta}_i$ is the number of differences at locus $i$. If we assume the loci are exchangeable, we have:

$$\text{Var} \left[ \hat{\theta}_{(n)} \right] = \frac{\text{Var} \left[ \hat{\theta}_i \right]}{n} + \frac{n-1}{n} \text{Cov} \left[ \hat{\theta}_i, \hat{\theta}_j \right].$$

This variance corresponds to the variation expected among independent outcomes of the evolutionary process, including the population pedigree. Under the standard coalescent model [Kingman 1982], $\hat{\theta}_i$ is Poisson distributed with mean $2\mu T_i$, where $T_i$ is the time until coalescence at locus $i$ in generations and $\mu$ is the mutation rate per locus per generation. Using the law of total covariance,

$$\text{Cov} \left[ \hat{\theta}_i, \hat{\theta}_j \right] = \mathbb{E} \left[ \text{Cov} \left[ \hat{\theta}_i, \hat{\theta}_j | T_i, T_j \right] \right]$$

$$+ \text{Cov} \left[ \mathbb{E} \left[ \hat{\theta}_i | T_i, T_j \right], \mathbb{E} \left[ \hat{\theta}_j | T_i, T_j \right] \right]$$

$$= 4\mu^2 \text{Cov} \left[ T_i, T_j \right],$$

since conditional on $T_i$ and $T_j$, $\hat{\theta}_i$ and $\hat{\theta}_j$ are independent. Thus,

$$\text{Var} \left[ \hat{\theta} \right] = \lim_{n \to \infty} \text{Var} \left[ \hat{\theta}_{(n)} \right] = 4\mu^2 \text{Cov} \left[ T_i, T_j \right].$$

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Because $T_i$ is distributed exponentially with rate $1/(2N_e)$ under the standard coalescent model \cite{Kingman1982,Tajima1983}, $\text{Var}[T_i] = 4N_e^2$. Since $\text{Cov}[T_i, T_j] = \text{Corr}[T_i, T_j] \times \text{Var}[T_i]$, we can write:

$$\text{Var}\left[\hat{\theta}\right] = (4\mu N_e)^2 \text{Corr}[T_i, T_j],$$

or

$$\text{Corr}[T_i, T_j] = \frac{\text{Var}\left[\hat{\theta}\right]}{\left[\text{E}\left[\hat{\theta}\right]\right]^2}$$

and we focus henceforth on the correlation of $T_i$ and $T_j$. Studying the correlation instead of the covariance also allows us later on to visually compare the results across different effective population sizes.

### 2.3 The effect of the sampling configuration

We now describe the six sampling configurations for a pair of unlinked loci in a sample of two sequences (Figure 2.1). Four of these sampling configurations involve a sample of two individuals, and we start by describing these.

In the first configuration, the loci are located effectively infinitely far apart on the same chromosome in both individuals. This means that these loci will be coupled for the first few generations, until separated by a recombination event. Once separated, they may later back-coalesce onto the same chromosome, and again resume percolating together through the pedigree for a period of time that is expected to be short. (In the event of back-coalescence, two ancestral loci not sharing genetic material come to be located on the same chromosome, which essentially undoes the effect of recombination.) In the second configuration, the loci are on different homologous chromosomes, meaning they will necessarily be present in different parents in the immediately preceding generation, as each chromosome was inherited from a different parent. It is then also possible for them to back-coalesce in later generations. The third configuration is a mixture of the first two: the loci are located on the same chromosome in one individual, and on homologous chromosomes in the other. In the fourth configuration, the loci are sampled from non-homologous chromosomes in both individuals. This configuration is different from the previous three in that back-coalescence is not
Figure 2.1: The different sampling configurations. Sampling configurations 1 to 4 involve a sample of two individuals, depicted by two circles. Sampling configurations 5 and 6 involve a single individual, depicted by a single circle. The lines within each circle correspond to two pairs of homologous chromosomes.
possible.

In the fifth and sixth sampling configurations, all sequences are sampled from a single individual. This is common in applications, in part because measuring the heterozygosity in a single individual does not require haplotype phasing. In configuration 5, we sample two loci from the same chromosome (and their pairs from the homologous chromosome). Given that each homologous chromosome must originate from a different parent, in one generation the sampled loci will transition to configuration 1 with probability $0.25$, to configuration 2 with probability $0.25$, and to sampling configuration 3 with probability $0.5$. In sampling configuration 6, the sampled loci are on different (non-homologous) chromosomes. This configuration is reduced in one generation to sampling configuration 4, and therefore has the same correlation properties as that configuration.

### 2.3.1 The DDTWF model

To study the correlation of coalescence times under the different sampling configurations, we use a DTWF model. This class of models has been advocated as an alternative to the coalescent when the sample size is large relative to the population size, as it can accommodate multiple and simultaneous mergers (Bhaskar et al., 2014).

In our case, we assume non-overlapping generations, a constant population size of $N_e$ diploid individuals, half of which are male and half of which are female, random mating between the sexes, no selection, and no migration. There are three possible types of events: recombination, coalescence, and back-coalescence. Because the population size is finite, combinations of these events can occur in a single generation. We also keep track of whether lineages are in the same individual or not, as this determines their trajectory in the immediately preceding generation. We refer to this model as the 2-sex DDTWF. Later we will consider a simplified (1-sex) DDTWF. The dynamics of this 2-sex DDTWF model can be summarized by a Markov transition matrix (Supplementary Material section 2.8.2) with 17 states, where the initial state is one of the sampling configurations 1, 2, 3, or 5.

This model is indeed only designed for pairs of loci sampled from either the same chromosome or homologous chromosomes, as the notions of back-coalescence and recombination only make sense
when this is the case. However, by modifying the interpretation of the states of the transition matrix, we can also model sampling configurations 4 and 6, which involve non-homologous chromosomes. This is because recombination for unlinked loci is indistinguishable from loci simply being located on two chromosomes inherited from the same parent but from different grandparents in terms of the path these loci take through the pedigree.

Given this transition matrix, we can write a system of equations using first step analysis for all states $x$ such that $E[T_iT_j|x] > 0$:

$$E[T_iT_j|x] = \sum_k p_{xk}E[(T_i + 1)(T_j + 1)|k]$$

$$= 1 + \sum_k p_{xk}E[T_i|k] + \sum_k p_{xk}E[T_j|k] + \sum_k p_{xk}E[T_iT_j|k]$$

$$= E[T_i|x] + E[T_j|x] + \sum_k p_{xk}E[T_iT_j|k] - 1,$$  \hspace{1cm} (2.7)

where $p_{xk}$ is the transition probability between states $x$ and $k$.

Solving this system of equations allows us to obtain exact results for $\text{Cov}[T_i, T_j|x]$. As a note, $E[T_i|x]$ can be different than $E[T_j|x]$ depending on the state $x$. For example, if the pair of lineages at locus $i$ is located on two different chromosomes in the same individual, whereas the pair of lineages at locus $j$ is located in two different individuals, then $E[T_i|x] = E[T_j|x] + 1$. To obtain the correlation, we can then normalize this covariance by the variance of the time until MRCA at a locus, which is the same regardless of whether the lineages were sampled from a same or from different individuals. This variance can also be calculated using the aforementioned system of equations with $i = j$.

Figure 2.2 shows the correlation of the time until MRCA for each sampling configuration. The highest correlation is found for configuration 1. As the two loci are located on the same chromosome in both sampled individuals, they must have originated from the same parent in the previous generation. Therefore, they either both coalesce or both do not, introducing correlation between the coalescent times. The effect of this sampling configuration then persists as long as there is no recombination. As $N_e$ increases, the probability of sampling closely related individuals decreases and the correlation decreases too, as it is much more likely for a recombination event to
Figure 2.2: Correlation of coalescent times for a sample of size 2. These correlations were calculated for different sampling configurations using the 2-sex DDTWF and the simplified DDTWF (described in detail in Supplementary Section 2.8.2). The different configurations in the legend are associated with the corresponding states of the Markov Chain, written in curly brackets, as described in the supplement.

occur before a coalescence event. Sampling configuration 3 (two loci located far apart on the same chromosome in one individual, and on different chromosomes in the second individual) shows the lowest correlation. In fact, it is slightly negative for very small values of \( N_e \), for if one of the loci coalesces in the first generation, then it is impossible for the other locus to coalesce. The correlation in other configurations is intermediate between those of configurations 1 and 3.

In figure 2.2, we also show the results from a simplified DDTWF model. This model is similar to the 2-sex DDTWF, except that individuals are monoecious and we do not keep track of whether lineages are in the same individual or not. There are much fewer states in this model than in the 2-sex DDTWF, and it is therefore significantly easier to analyze. The simplified model turns out as a very good approximation to the 2-sex DDTWF, even for moderately large \( N_e \). More details on both models are given in Supplementary Material sections 2.8.2.
2.4 The effect of the shared pedigree

The 2-sex DDTWF model allows us to calculate exactly the correlation of coalescence times at two loci. In this section, we aim to provide more intuition with regard to the role of the shared underlying pedigree in generating positive correlations of coalescent times.

2.4.1 Inconsistency of $\hat{\theta}$ due to the underlying pedigree

The value of $\hat{\theta}$ is a function of the pedigree that connects the two individuals in our sample, where the pedigree itself is randomly drawn from from a demographic model (e.g., the Wright-Fisher model). If the sampled individuals happen to be more closely related than average, then $\hat{\theta}$ will tend to underestimate the true value of $\theta$. The opposite is true if the sampled individuals are less closely related than average.

Let $\delta$ be the probability that a randomly sampled pair of individuals is very closely related, for example as full siblings. Let $\epsilon$ be some arbitrary value smaller than the difference between $\theta$ and $\hat{\theta}^*$, where $\hat{\theta}^*$ is estimated from a sample of full siblings. By sampling sufficiently many loci (or gene genealogies), we could theoretically infer the common ancestry of the sampled pair to any desired accuracy. However, this would not give information about the pedigree beyond the ancestry of the sampled pair, and as the sampled pair is related more closely than average, $\hat{\theta}^*$ would underestimate $\theta$. For this fixed $\epsilon$ and $\delta$, we therefore cannot find $n$ large enough such that $\text{Prob}(|\hat{\theta}^*_{(n)} - \theta| > \epsilon) < \delta$. This implies that there is no convergence in probability, which means that this estimate of $\theta$ is not consistent. In turn, this inconsistency implies that the variance of $\hat{\theta}_{(n)}$ does not tend to 0 as $n$ increases.

As a note, since the pedigree itself is the product of a stochastic model (Wright-Fisher or otherwise), even a fully specified pedigree leaves uncertainty regarding the value of $\theta$. In other words, the uncertainty in the estimate of $\theta$ results from having at hand only a single sample from a single pedigree generated from a stochastic model that is governed by that parameter (see also [Ralph (2015)].)
2.4.2 A lower bound on the limiting variance

Here, we analytically calculate a lower bound on the limiting variance of $\hat{\theta}$ in the case of non-homologous chromosomes, in a way that provides an intuitive understanding of the effect of the shared pedigree. We compute the covariances of $T_i$ and $T_j$ by conditioning on a vector of variables $\{x\} = x_1, x_2, \ldots, x_G$, where $x_g$ is the number of shared ancestors $g$ generations ago. This vector $\{x\}$ is in a sense a lower dimensional representation of the shared pedigree, and can be used to approximate the probability of coalescence each generation. For example, if $x_1 = 2$ (full siblings), then all loci have the same 25% probability of coalescing within a single generation. We only consider the first $G = \log_2 N$ generations, where $N$ is the (constant) effective population size, as it was shown that the effect of the shared pedigree is important only up to $\approx \log_2 N$ generations (Wakeley et al., 2012; Derrida et al., 2000; Chang, 1999). Beyond that time, almost all ancestors are shared, and the distribution of the contributions of each ancestor to the present day sample is approximately stationary.

By the law of total covariance, we have:

$$
\text{Cov}[T_i, T_j] = E_{\{x\}}[\text{Cov}[T_i, T_j|\{x\}]]
+ \text{Cov}_{\{x\}}[E[T_i|\{x\}], E[T_j|\{x\}]]. \quad (2.8)
$$

$E_{\{x\}}[\text{Cov}[T_i, T_j|\{x\}]] \approx 0$, because conditioning on the pedigree, the loci are independently segregating. Therefore:

$$
\text{Cov}[T_i, T_j] = \text{Cov}_{\{x\}}[E[T_i|\{x\}], E[T_j|\{x\}]]= \text{Var}_{\{x\}}[E[T_i|\{x\}]]. \quad (2.9)
$$

To compute $E[T_i|\{x\}]$, we condition on whether coalescence has occurred in the first $G$ generations. If it has not occurred, we assume that the process then behaves just as the standard coalescent, or
\[ E[T_i|\text{no coal}] = 2N + G. \] We can write:

\[
E[T_i\{x\}] = (2N + G)P(\text{no coal by } G\{x\}) \\
+ \sum_{g=1}^{G} gP(\text{coal at } g\{x\}). \tag{2.10}
\]

As computed in [Wakeley et al. (2012)], the coalescence probability is roughly given by
\[ P(\text{coal at } g\{x\}) = \alpha(g) \prod_{g'=1}^{G-1} [1 - \alpha(g')], \]
where \( \alpha(g) = x_g/2^{2g+1} \) and \( \text{Prob} \{ \text{no coal by } G\{x\} \} = \prod_{g=1}^{G} [1 - \alpha(g')]. \)

Since \( \alpha(g) \ll 1 \) (see below), we approximate \( P(\text{coal at } g\{x\}) \approx \alpha(g) \) and \( P(\text{no coal by } G\{x\}) \approx 1 - \sum_{g=1}^{G} \alpha(g). \) Thus,

\[
E[T_i\{x\}] \approx (2N + G) - \sum_{g=1}^{G} (2N + G - g) \alpha(g) \tag{2.11}
\]

and

\[
\text{Var}_{\{x\}}[E[T_i\{x\}]] \approx \text{Var} \left[ \sum_{g=1}^{G} (2N + G - g) \alpha(g) \right] \\
\approx 4N^2 \text{Var} \left[ \sum_{g=1}^{G} \frac{x_g}{2^{2g+1}} \right], \tag{2.12}
\]

since \( G \ll N. \)

While the \( x_g \)'s are clearly positively correlated, we make the approximation that they are independent. (In Supplementary Material sections S-3, S-4 and S-5, we provide a numerical method to calculate the exact covariances of the \( x_g \)'s.) Under the assumption of independence, we have the following lower bound on the overall variance in Eq. (2.12),

\[
\text{Var}_{\{x\}}[E[T_i\{x\}]] \gtrsim N^2 \sum_{g=1}^{G} \frac{\text{Var}[x_g]}{2^{4g}}. \tag{2.13}
\]

To compute the variance of \( x_g \), we note that the distribution of \( x_g \) is roughly hypergeometric with parameters \( 2^g \) potential successes, \( N - 2^g \) potential failures, and \( 2^g \) draws, giving \( \text{Var}[x_g] \approx 2^{2g}(N-2^g)^2/N^3 \). (We expect deviations from the hypergeometric to be largest for small populations
sizes, because the number of ancestors in generation $g$ is less than $2^g$ more often in very recent generations in small populations. We provide the exact distribution of the variance of $x_g$ in the Supplement sections S4, S5 and S6). Substituting in Eq. (2.13),

$$\text{Var}_{\{x\}} \left[ \mathbb{E} \left[ T_i \mid \{x\} \right] \right] \geq \frac{1}{N_e} \sum_{g=1}^{G} \frac{(N - 2^g)^2}{2^{2g}}. \quad (2.14)$$

Using $G = \log_2 N$, we have $\sum_{g=1}^{G} \frac{(N - 2^g)^2}{2^{2g}} = \left( \frac{N^2}{3} - 2N + \frac{3 \log N}{\log 8} + \frac{5}{3} \right) \approx \frac{N^2}{3}$ for large $N$, and hence, using Eq. (2.9),

$$\text{Cov} \left[ T_i, T_j \right] \gtrapprox \frac{N}{3}. \quad (2.15)$$

Using Eq. (2.4) and $\theta = 4\mu N$, we finally obtain

$$\text{Var} \left[ \hat{\theta} \right] \gtrapprox \frac{\theta^2}{12N}. \quad (2.16)$$

In summary, the variance due to the shared pedigree adds a term of order at least $\theta^2/N$, independently of the number of regions $n$. Thus, as argued in the previous section, even for a large number of chromosomes the variance does not decay to zero, but rather to a constant that depends on the effective population size.

### 2.5 Simulations

#### 2.5.1 Wright-Fisher simulations

In this section, we use simulated data to support our analytical results from sections 2.3.1 and 2.4.2. To estimate the correlation of coalescence times at two loci, we first simulate many Wright-Fisher pedigrees and sample two individuals from the current generation for each pedigree. We set the population size $N$ to be the same in every generation, with equal numbers of males and females. We then consider two loci on non-homologous chromosomes and simulate the path through the pedigree connecting the two lineages at each locus to their MRCA. In each generation and for each locus, lineages that are found in the same individual coalesce with probability 1/2, in
which case the coalescence time is recorded. Loci on different chromosomes in the same individual neither coalesce in that generation nor in the previous generation. We repeat this process multiple times for each pedigree to obtain an estimate of $E[T_{\text{ped}}]$. We then compute its variance over many simulated pedigrees to obtain $\text{Var}_{\text{ped}}[E[T_{\text{ped}}]]$. By the same logic as Eq. (2.9) above, $\text{Var}_{\text{ped}}[E[T_{\text{ped}}]]$ is equal to $\text{Cov}[T_i, T_j]$. To obtain the correlation, we divide $\text{Cov}[T_i, T_j]$ by $\text{Var}[T] = \text{Var}_{\text{ped}}[E[T_{\text{ped}}]] + E_{\text{ped}}[\text{Var}[T_{\text{ped}}]]$.

The total correlation calculated by simulating over many Wright-Fisher pedigrees is exactly equivalent to the results from the 2-sex DDTWF. The lower bound in Eq. (2.16) combined with Eq. (2.6), result in the bound $\text{Corr}[T_i, T_j] \geq 1/(12N)$. This approximate result is also well supported by simulations, as illustrated in Figure 2.3.

### 2.5.2 Simulations based on real pedigrees

The Wright-Fisher model is only one way to generate pedigrees under a given effective population size. Real human pedigrees have complex structures that depend on the geographical region. For
example, there are different rates of consanguineous marriages in different countries (Bittles and Black, 2015), different distributions of the number of children per family, and different mating structures (leading to differences in the number of full-siblings and half-siblings). To gain insight on the effect of these differences on the ability to estimate $\theta$, we construct a Wright-Fisher-like model, but which is constrained by patterns of real human pedigrees. Specifically, we use the Familinx database, compiled by Erlich (2015), which carries information on about 44 million individuals from different countries.

We extracted genealogical data for three countries (Kenya, Sweden, USA) from Familinx. We then used these data to simulate pedigrees by breaking down and reassembling small family units, as previously described for a different dataset (Wakeley et al., 2012). Specifically, we first split the genealogies into two-generational family units of children and their parents. To belong to a unit, a child must share at least one parent with at least one other child in the family unit. Because Familinx contains data on more than the three countries we chose, in order not to create a bias in favor of smaller, simpler family units, we only require that the first sampled child be in the corresponding country data set. These family units then serve as building blocks to generate pedigrees with the same mating patterns and distribution of the number of children as in the reference population. We generated pedigrees with a pre-specified effective population size $N_e$ in a range from 20 to 140. The census population size that corresponds to this $N_e$ was determined by simulation for each country by averaging the time until coalescence across randomly sampled pairs and across pedigrees. Clearly, some information is lost in breaking large genealogies into family units, such as inter-generational correlations in family size, or the rate of first and second cousin matings. Nevertheless, sufficient information is captured so that pedigrees with the same $N_e$ built using data from different countries can be distinguished based on the correlation of coalescent times. Once the pedigrees were generated, we simulated genealogies through those pedigrees as described in section 2.5.1. Additional details on the simulations are provided in the Supplement section S1.

For each country and $N_e$, we then use the simulated data to compute the correlation of coalescence times, as in section 2.5.1 (i.e., $\text{Var}_{\text{ped}} [E[T|\text{ped}]]$ divided by $\text{Var}[T]$). The results (Figure
Figure 2.4: We simulate the correlation of the time until MRCA in pedigrees constructed using country specific data from the Familinx dataset. The correlation of the time until MRCA at unlinked loci on non-homologous chromosomes varies depending on the structure of the pedigree in ways that cannot be summarized by $N_e$.

2.4 demonstrate that $\text{Corr} \left[ T_i, T_j \right]$ (and consequently, $\text{Var} \left[ \hat{\theta} \right]$) vary between populations, and are higher in the Familinx-inspired model compared to the expectation from the Wright-Fisher model. The difference is plausibly because in the Wright-Fisher model, the ratio of half siblings to full-siblings is much higher than in the human pedigrees. This implies higher variance in the degree of relatedness in many real-world pedigrees relative to Wright-Fisher pedigrees. Therefore, it would be more difficult to estimate $\theta$ (i.e., higher variance of $\hat{\theta}$) in real-world populations than based on the expectation from the Wright-Fisher model. Further deviations are expected if we were to impose realistic first-cousin mating rates (Bittles and Black 2015).

2.6 Linked sites and model comparisons

The DDTWF models can be relatively easily extended to the case of linked sites. This is because the transition probabilities are expressed in terms of the per generation recombination probability
Figure 2.5: We calculate correlations from the 2-sex DDTWF model for different values of $N\rho$. These overlap perfectly with the results from our Wright Fisher simulations. Loci were assumed to be sampled in sampling configuration 1.

$r$, which has so far been set to 0.5, but which can also be set to values less than 0.5 (see Supplemental Material section S-2). The pedigree simulations can also accommodate probabilities of recombination less than 0.5, and align very well with the results from simulations, as expected (see Figure 2.5). We can therefore compare the exact 2-sex DDTWF model to the coalescent with recombination and its Markovian approximations. While it is true that the pedigree plays a role in determining the shape of gene genealogies, and that the 2-sex DDTWF model is the most accurate model in the absence of knowledge of the underlying pedigree, the difference between this model and other more simplified models may be negligible.

Let $r$ be the recombination rate, i.e. the probability that two loci on the same chromosome descend from different chromosomes in the previous generation, and let $\rho = 4Nr$. Under the ancestral recombination graph (ARG) [Griffiths and Marjoram 1997], which is the standard model for the coalescent with recombination, the gene genealogy of the sample at a given locus depends on
all previous genetic ancestries along the sequence (Wiuf and Hein 1999). The covariance satisfies (e.g., Simonsen and Churchill 1997),

\[
\text{Cov}_{\text{ARG}}[T_i, T_j] = \frac{18 + \rho}{18 + 13\rho + \rho^2}. \tag{2.17}
\]

In contrast, under the Sequentially Markov Coalescent (SMC) (McVean and Cardin 2005), each new genealogy (following recombination) depends only on the previous genealogy, and the new coalescence time must differ from the previous time (no back-coalescence allowed). In this case, we have:

\[
\text{Cov}_{\text{SMC}}[T_i, T_j] = \frac{1}{1 + \rho}. \tag{2.18}
\]

The SMC’ model (Marjoram and Wall 2006) is a variant of SMC where back-coalescence is allowed. Under SMC’ (Eriksson et al. 2009; Wilton et al. 2015),

\[
\text{Cov}_{\text{SMC}'}[T_i, T_j] = 2^{\rho/2} e^{-\rho/4} (-\rho)^{-1/2-\rho/4} \times \left[ \Gamma \left( \frac{2 + \rho}{4} \right) + \Gamma \left( \frac{2 + \rho}{4}, -\frac{\rho}{4} \right) \right]. \tag{2.19}
\]

The covariances of coalescent times derived from the ARG, the SMC, and the SMC’ are expected to be equal to the correlations of coalescent times (because \( T_i \) and \( T_j \) are assumed to be exponentially distributed with rate 1). In Figure 2.6, we compare the correlation of \( T_i \) and \( T_j \) as a function of \( \rho \) for different values of \( N_e \) and \( r \) across the different models. Compared to the full 2-sex DDTWF model, the simplified DDTWF is an extremely good approximation even for \( N_e \) as small as 100. The maximum difference in correlation between these two models across the range of values of \( \rho \) in Figure 2.6 was less than .005. Therefore, the simplified model may be preferred due its much reduced complexity (see also figure 2.2). The ARG also provides a very good approximation under these conditions. In turn, the SMC’ model shows slight deviations compared to the ARG, while, as previously shown, the SMC model deviates more substantially (Wilton et al. 2015). For \( N = 10 \), we observe a small but noticeable difference between the 2-sex and simplified DDTWF models, where the maximal difference in correlation is around .025, and between these models and the
Figure 2.6: We plot the correlations of coalescent times predicted by the ARG, the SMC, the SMC’ and the 2-sex DDTWF with $N = 100$, across a range of different values of $N\rho$. The predictions of the coalescent and the SMC’ are very good approximations for those of the 2-sex diploid Markov Chain model for big enough values of $N_e$, such as $N = 100$.

2.7 Discussion

It is known that increasing the size of the sample has limited ability to improve estimates of $\theta$, as the individuals in the sample share most of their genealogy (Rosenberg and Nordborg 2002). For this reason, it has been recommended to use sequencing data from many unlinked gene loci from a small sample of individuals (Felsenstein 2006). While this intuition still holds, we have shown that the estimator of $\theta$ based on pairwise differences at many loci is not consistent and has non-zero variance even when sampling infinitely many loci. Fundamentally, this results from the (weak) dependence of the coalescence times even at unlinked loci due to the underlying shared pedigree.

We further showed that the sampling configuration can significantly affect the correlation of
coalescence times, as it restricts the number of available gene genealogies for each pair of loci. We studied in detail the possible ways by which two loci could be sampled from two sequences and computed the correlation of the coalescence times for each configuration.

Even with sampling configurations where loci can truly travel independently through the pedigree, we still observe positive correlation across loci. This is because the pedigree that connects any pair of individuals is invariant across loci, inducing correlation between the coalescence times at those loci. We used this view to obtain a lower bound on the covariance of coalescence times, by explicitly conditioning the number of ancestors the two individuals share in the first few generations. The shared pedigree itself is assumed to be a single draw from a random demographic process (Wright-Fisher or another), with some characteristic effective population size. Even if we were able to perfectly characterize the single pedigree at hand, we cannot hope to infer with complete certainty the parameters of the demographic model. It is worth noting, however, that one can adopt a different (philosophical) view, under which the pedigree itself is the subject of inference, and is not a product of a random demographic process (Ralph, 2015). Under such a view, there are no estimators of \( \theta \) (or of an effective population size).

The analytical results in this paper are based on the Wright-Fisher model. To gain insight on the behavior of more realistic demographic models, we adapted the Wright-Fisher model according to the family structure of real human populations. The results demonstrated that the correlation of coalescence times is higher in the human-inspired models than in the WF model; therefore, \( \theta \) should be more difficult to estimate than expected under the pure WF model.

The existence of a detailed pedigree for the sample at hand can be useful when studying the population dynamics (e.g., Moreau et al., 2011) without resorting to somewhat arbitrary demographic models. When using models, it is not always clear whether it is necessary to retain all features of the real population (two sexes, diploidy, etc.), or whether a simplified model could display similar characteristics. We used our analytical framework to study the correlation of coalescence times as a function of the scaled recombination rate \( \rho \) for the 2-sex and the simplified DDTWF models, and compared the results to the coalescent with recombination and its Markovian approximations. We found that as expected, unless the effective population size is extremely small \( (N \leq 10) \), the results
for the coalescent (as well as its SMC’ approximation, but not SMC) were extremely close to those of the DDTWF models. In contrast, differences were observed for $N = 10$, even between the 2-sex and the simplified DDTWF.

Finally, we have focused on a sample of two individuals at two loci. For unlinked loci, we showed that the variance of $\hat{\theta}$ for any number of loci is reduced to the two-loci problem. Extending the sample size to more than two individuals is expected to be significantly more complicated. Deviations between the coalescent and the discrete time haploid Wright-Fisher model for increasing sample sizes were recently studied and shown to be important for realistic human demographic histories (Bhaskar et al., 2014). We similarly expect the presence of a shared pedigree to have an increasingly significant effect on the variance of Tajima’s estimator as the sample size grows, but this analysis is left for future studies.
2.8 Extended methods and analytical results

2.8.1 Building pedigrees with Familinx

We simulate our pedigree over $GEN = 100$ non-overlapping generations. For each generation, we select at random family units from the data until the total number of children across all of these family units is greater than some pre-determined $N$, and the total number of parents is less than or equal to $N$. Then, we connect the $GEN$ generations together by randomly assigning each parent in generation $g$ to be one of the children in generation $g + 1$, disallowing sibling mating. Finally we connect the first and last generation so that the pedigree is cyclical with a period of $GEN$ generations.

As a note, this procedure will not be appropriate for datasets where a substantial number of family units contain only one child because the algorithm requires a number of children greater than or equal to the number of parents. Families with many children will be over-sampled, and the family structure of the constructed pedigrees will be very different from the family structure we are attempting to replicate.

The value of $N$ was determined to correspond on average to a certain target effective population size $N_e$. We estimate the $N_e$ for each constructed pedigree by simulating the average time until coalescence over 50 sampled pairs. We discard pedigrees whose estimated effective population size is not within $\sigma_{N_e}$ of the target $N_e$, where $\sigma_{N_e}$ is the standard deviation of the observed coalescent effective sizes for a population of size $N = N_e$ in the Wright-Fisher model. We constrain our pedigrees to be close to the target effective population size because we want to make sure that the higher total covariance we observe in the Familinx pedigree simulations relative to the Wright Fisher is not only due to potentially higher variance of $N_e$.

2.8.2 The DDTWF models

The 2-sex DDTWF transition matrix

The notation we use to label the states in the 2-sex DDTWF transition matrix is derived from the notation of Wakeley and Lessard (2003), who built a similar transition matrix to analyze patterns
of linkage disequilibrium in a 2-locus multi-deme model. We detail this notation in supplementary figure 2.7.

Consider two copies of a first locus, ‘1’, located in two different individuals. On the same chromosomes as the copies of this first locus are copies of a second locus, ‘2’. This is our sampling state, which we represent as \(\{12,12\}\). The comma separates the different chromosomes on which there is followed genetic material. We distinguish this state from \(\{(12,12)\}\), the parentheses indicating that the followed pairs of loci are present on two different chromosomes in the same individual. If the followed lineages are on different chromosomes in the same individual, then they must be located in different individuals in the previous generation. So, for example, state \(\{(1,1)\}\) (which is the state where the two copies of locus ‘2’ have coalesced, and the two copies of locus ‘1’ are in the same individual on different chromosomes) automatically transitions to state \(\{1,1\}\) in one generation.

The set of all possible states in our model is: \(\{\}\), \(\{1,1\}\), \(\{2,2\}\), \(\{(1,1)\}\), \(\{(2,2)\}\), \(\{1,1,2,2\}\), \(\{(1,1),2,2\}\), \(\{1,1,(2,2)\}\), \(\{(1,2),(2,2)\}\), \(\{1,1,(2,2)\}\), \(\{(1,2),(1,2)\}\), \(\{1,1,1,1\}\), \(\{1,2,1,2\}\), \(\{(12,1),2\}\), \(\{(12,2),1\}\), \(\{12,(1,2)\}\), \(\{12,(1,2)\}\) and \(\{(12,12)\}\). We show the communicating states in this transition matrix in table 2.1.
Figure 2.7: States of the 2-sex DDTWF model. Circles represent individuals; the two lines within each individual represent a pair of homologous chromosomes; the square represents the first followed locus and the diamond represents the second followed locus. \{12,12\} corresponds to sampling configuration 1, and is the sampling state we use to calculate correlations of coalescent times.
### 2.8.3 The simplified DDTWF transition matrix

We also consider a simplified version of this model, a monoecious bi-parental DDTWF model. In this model, we do not keep track of whether lineages are in the same individual or not. The diploidy only comes into play in that recombination is impossible in a haploid context. For this reason, this model can only be used to show the effect of a limited number of sampling configurations. For example, it is not possible to model sampling configuration 2, where loci are sampled from different homologous chromosomes in the same individual. The complete list of states in this model is: \( \{ \}, \{1,1\}, \{2,2\}, \{1,1,2,2\}, \{12,1,2\}, \text{ and } \{12,12\} \), far fewer than in the 2-sex DDTWF model. We show a matrix of communicating states in table 2.2.

### 2.8.4 Expected generation time in both models

If two loci are located in two different individuals, then the probability they coalesce in a single generation is just \( 1/2N \). However, if they are present in different chromosomes of the same individual, they must have originated in two different individuals in the previous generation. Because of this, the expected time until coalescence will be different than \( 2N \) in the 2-sex DDTWF, as opposed to in the simplified DDTWF where it is just equal to \( 2N \).

The process retains some memory of the fact that loci were initially sampled in two different individuals. Indeed, the time until coalescence at generation \( g \) given no coalescence in any previous generation will be different than the expected time until coalescence at generation \( g + 1 \), given no coalescence in any previous generation. As \( g \) increases, this difference in coalescent times decreases.
from one generation to the next, and the process converges to an average generation time.

Consider a sampled pair of genes in two individuals. In generation $g+1$, given that no coalescent events occurred in any of the previous $g$ generations, the probability that the two followed lineages coalesce is

$$C(g + 1) = \frac{1}{4} P(F(g)|\text{No Coal}) + \frac{1}{8} P(H(g)|\text{No Coal}),$$

where $P(F(g)|\text{No Coal})$ and $P(H(g)|\text{No Coal})$ are the probabilities that the two lineages are located in full siblings and half siblings respectively in generation $g$, given no coalesce in that generation or any of the previous generations. In addition, we have

$$P(F(g)|\text{No Coal}) = \frac{1 - 2C(g)}{1 - C(g)} \frac{1}{(N/2)^2},$$

where the term $1 - 2C(g)$ is the probability that the two lineages are in different individuals, and the denominator $1 - C(g)$ arises because we are conditioning on no coalescence in generation $g$. The probability that two lineages located in different individuals share exactly two parents is $\frac{1}{(N/2)^2}$. In the same way, we have:

$$P(H(g)|\text{No Coal}) = \frac{1 - 2C(g)}{1 - C(g)} \frac{2}{N/2 - 1} \frac{N/2}{N/2},$$

By solving $C(g + 1) = C(g)$, we obtain the limiting coalescent probability as a function of $N$. As the distribution of the time until MRCA follows a geometric distribution, the generation time is the inverse of the probability of coalescence each generation, or

$$E[T_i] = \frac{2N}{1 + N - \sqrt{1 + N^2}}.$$

This generation time is always slightly greater than $2N$. $\frac{E[T_i]}{2N}$ quickly converges to 1 as $N$ becomes large.
2.8.5 Distribution of the number of ancestors from one generation to the next

Consider a single individual in the population with non-overlapping generations in a 2-sex model. Each generation \( g \), there are \( N_{fg} \) males and \( N_{mg} \) females. Let \( y_g \) be the number of ancestors of a particular individual at generation \( g \) in the past. During the first few generations, the number of ancestors grows very fast, and we expect \( y_g \approx 2^g \). As the number of ancestors in a given generation starts to approach the size of the population, the ancestors overlap with one another, and the growth of ancestors slows down until an equilibrium distribution is reached. We are interested in modeling the exact distribution of the number of ancestors in generation \( g + 1 \), \( y_{g+1} \), given the number of ancestors in generation \( g \), \( y_g \).

We can first divide the number of ancestors in generation \( g + 1 \) into males and females:

\[
y_{g+1} = F + M,
\]

where \( F \) is the number of fathers of individuals in \( y_g \), and \( M \) is the number of mothers of individuals in \( y_g \).

We have

\[
P(F = f|y_g) = \frac{\binom{N_{f(g+1)}}{f} f! S_2(y_g, f)}{(N_{f(g+1)})^{y_g}}
\]

where \( S_2 \) is the Stirling number of the second kind. The intuition behind this formula is that there are \( \binom{N_{f(g+1)}}{f} \) possible ways of choosing \( f \) fathers among the \( N_{f(g+1)} \) available. There are then \( f! \) possible orderings of these chosen males. The Stirling number of the second kind is the number of ways we can partition a set of \( y_g \) individuals into \( f \) categories. We divide all this by the total number of ways of making \( y_g \) choices of fathers among the \( N_{f(g+1)} \) available, or \( (N_{f(g+1)})^{y_g} \).

Likewise,

\[
P(M = m|y_g) = \frac{\binom{N_{m(g+1)}}{m} m! S_2(y_g, m)}{(N_{m(g+1)})^{y_g}}.
\]

We then obtain the following convolution for the number of ancestors \( a \) in generation \( g + 1 \):

\[
P(y_{g+1} = a|y_g) = \sum_{f=1}^{a-1} P(F = f|y_g)P(M = a - f|y_g).
\]
\(y_1, \ldots, y_G\) form a Markov Chain. Using the preceding formula, we can create a transition matrix \(y_{g+1}\) given \(y_g\).

If we didn’t have a two sex model, but instead a bi-parental monoecious model, the formula for the number of ancestors in generation \(g + 1\) would be the following simpler expression:

\[
P(y_{g+1} = a|y_g) = \frac{(N_a)! S_2(2y_g, a)}{N_{g+1}^2 y_g a!}.
\]

### 2.8.6 Overlap in the number of ancestors each generation

In the previous section, we described the distribution of the number of ancestors each generation. Here, we start with a sample of size 2 individuals, A and B, and are interested in the distribution of the number of shared ancestors each generation. If this sample consists of a pair of full siblings, then the number of shared ancestors grows according to the formula provided in the previous section, as full siblings share all of their ancestors in common.

Let \(X_g\) be the set of common ancestors in generation \(g\). Let \(A_g\) be the ancestors of A that are not in \(X_g\), and \(B_g\) be the set of ancestors of B that are not in \(X_g\). Let \(|A_g|, |B_g|\) and \(|X_g|\) be the cardinality of these three disjoint sets.

Let \(F_A\) be the set of fathers of individuals in \(A_g\), and let \(|F_A|\) be the cardinality of \(F_A\). Likewise we define \(F_X, F_B, |F_X|,\) and \(|F_B|\). Given \(|A_g|, |B_g|,\) and \(|X_g|\), the distribution of \(|F_A|, |F_B|,\) and \(|F_X|\) is as described in the previous section. That is, we have:

\[
P\left(|F_A| = f \mid A_g\right) = \binom{N}{f} f! S_2(|A_g|, f) N_{f(g+1)}^{|A_g|},
\]

\[
P\left(|F_B| = f \mid B_g\right) = \binom{N}{f} f! S_2(|B_g|, f) N_{f(g+1)}^{|B_g|},
\]

and

\[
P\left(|F_X| = f \mid X_g\right) = \binom{N}{f} f! S_2(|X_g|, f) N_{f(g+1)}^{|X_g|}.
\]

The number of fathers in common between individuals in \(A_g\) and \(X_g\), \(xa\), follows a hypergeometric distribution with \(F_X\) success states, \(N_{f(g+1)} - |F_X|\) failure states, and \(|F_A|\) draws.
The probability that individuals in $B_g$ have $xb$ fathers in common with individuals in $X_g$, and $ba$ fathers in common with individuals in $A_g$, given that $|F_A \cap F_X| = xa$, is defined by a trivariate hypergeometric distribution:

$$P \left( |F_B \cap F_X| = xb \text{ and } |F_B \cap F_A| = ab \mid |F_A \cap F_X| = xa \right) = \frac{\binom{|F_X|}{xb} \binom{(N_f(g+1)-|F_X|)}{ab}}{\binom{N_f(g+1)}{|F_B|-xb-ab}}.$$ 

The number of shared male ancestors in generation $g+1$ is $|X_{f(g+1)}| = |F_X| + ab$, the number of male ancestors exclusive to $A$ is $|A_{f(g+1)}| = |F_A| - ab - xa$, and the number of male ancestors exclusive to $B$ is $|B_{f(g+1)}| = |F_B| - ab - xb$.

To obtain the number of shared female ancestors, $X_{m(g+1)}$, we use the same protocol, except replacing $N_f(g+1)$ by $N_m(g+1)$. Finally, to derive the joint distribution of $X_{g+1}$, $A_{g+1}$ and $B_{g+1}$, we take the convolution over the number of male and female ancestors.

In this way, we can derive a transition matrix $T$. The entries $T_{ij}$ of the transition matrix give the probability of entering state $j = (|A_{g+1}|, |B_{g+1}|, |X_{g+1}|)$ given state $i = (|A_g|, |B_g|, |X_g|)$.

We plot the dynamics of the number of shared ancestors every generation in figure 2.8. The distribution of the number of shared ancestors in generation $g$ is obtained by considering the $g$-th power of $T$, assuming a sampling configuration of $(1,1,0)$ and then summing over the probabilities of all configurations with same $|X_g|$.

If instead of having a two sex model, we simply had a bi-parental model, then the distribution of the possible configurations in generation $g+1$, given the configuration in generation $g$ would be:

$$P (|K_B \cap K_X| = xb \text{ and } |K_B \cap K_A| = ab \mid |K_A \cap K_X| = xa) = \frac{\binom{|K_X|}{xb} \binom{((K_A \cap K_X \cap K_B)|}{ab} \binom{(N_f(g+1)-(|K_A \cup K_X|))}{|K_B|-xb-ab}}{\binom{N_f(g+1)}{|K_B|}},$$

where $K_A$, $K_B$ and $K_X$ are the parents of individuals in $A_g$, $B_g$, and $X_g$ respectively.
Figure 2.8: The process reaches an equilibrium distribution after about 7 generations for $N = 8$.

### 2.8.7 Variance and covariances of the number of ancestors each generation

We can calculate the covariances between the number of shared ancestors in generations $i$ and $j$, $\text{Cov}(X_i, X_j)$, using the transition matrix $T$, derived as described in the previous section. Let state 0 be the index of the sampling configuration, $(1, 1, 0)$ We have for $i \leq j$:

\[
\text{Cov}[X_i, X_j] = \mathbb{E}[X_i X_j] - \mathbb{E}[X_i] \mathbb{E}[X_j] = \mathbb{E}[X_i \mathbb{E}[X_j|X_i]] - \mathbb{E}[X_i] \mathbb{E}[X_j]
\]

\[
= \sum_{z=0}^{N} \left( z P(X_i = z) \sum_{k=0}^{N} k P(X_j = k|X_i = z) \right) - \sum_{z=1}^{N} z P(X_i = z) \sum_{z=1}^{N} z P(X_j = z).
\]

There are a number of states in the transition matrix which correspond to a same number of shared ancestors $z$. We refer to the set of these states as “Conf $z$”. Therefore,

\[
P(X_i = z) = \sum_{z_i \in \text{Conf } z} T^i[0][z_i]
\]

and

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Figure 2.9: In the left figure, we show the covariance of the number of ancestors each generation for \( N = 10 \). The diagonal represents the variance of the number of shared ancestors each generation, and is highest in generations 3, and 4. In the right figure, we show the correlations. The correlation between \( X_i \) and \( X_{i+1} \) is greater for small generations \( i \).

\[
\sum_{z=0}^{N} \left( zP(X_i = z) \sum_{k=0}^{N} kP(X_j = k|X_i = z) \right) = \sum_{z=0}^{N} z \sum_{z_i \in \text{Conf } z} \sum_{k=0}^{2N} T^i[0][z_i] \sum_{k_i \in \text{Conf } k} T^{i-1}[z_i][k_i].
\]

We plot the covariances and correlations for \( N = 10 \) in figure 2.9.

### 2.8.8 SMC and SMC’ simulations run through a fixed pedigree

The genealogy-building process that we have so far used is exactly analogous to the two-locus ancestral recombination graph with discrete loci (Griffiths and Marjoram, 1997) in the context of a fixed pedigree. In order to demonstrate the effect of back-coalescence for linked sites, we also consider two alternative genealogy building algorithms, essentially transposing the SMC (McVean and Cardin, 2005) and the SMC’ (Marjoram and Wall, 2006) models to fixed pedigree simulations. In the SMC’ inspired model, lineages are only allowed to back-coalesce to the locus with which
they were previously linked. That is, no lineage shuffling is allowed. In the SMC inspired model, it is not possible to back-coalesce at all (Holboth and Jensen, 2013). In all of these simulations, any amount of assorting of the genetic material in between the two followed loci is ignored.

In the context of the fixed pedigree, the SMC can be seen as a mixture of sampling configuration 1 and sampling configuration 4. Indeed, the loci are sampled in configuration 1. They travel together until a recombination event occurs, at which point they may no longer back-coalesce. After a recombination event, the loci behave as if they were sampled in configuration 4.

The SMC’, applied to a fixed pedigree, behaves in a more complicated manner. The loci are sampled in sampling configuration 1. We can consider the loci to be on homologous chromosomes until both pairs of loci are separated by recombination. At this point, the loci that were previously attached behave as in sampling configuration 1, and the other two possible pairs of loci containing non-overlapping ancestral material behave as if they were in configuration 4, that is sampled from non-homologous chromosomes.

The results for linked loci agree with findings by Holboth and Jensen (2013) without a fixed pedigree in that the SMC’ is a close approximation to the complete model, whereas the SMC model is far less accurate (see figures 2.10). The fixed pedigree SMC-inspired simulation has lower covariance than the two other models. This is intuitive as back-coalescence means previously independent loci become dependent once again, and the probability of back-coalescence is on the same order of magnitude as coalescence. This difference holds for small populations ($N = 10$) as well as larger ones ($N = 100$). However, limiting back-coalescence to disallow lineage shuffling only slightly decreases covariance, and seems to be a good approximation for the full model.

### 2.8.9 Total covariance decomposed in its constituent parts using Familinx data for linked loci

In supplementary figures 2.11 and 2.12, we can see that for linked loci the total covariance does not vary much across pedigrees built using families sampled from different populations. The variance in means is very affected by population structure, but is only a small component of the total covariance.
Figure 2.10: Differences in covariances obtained via fixed pedigree simulations using different models – the complete model, the SMC model, and the SMC' model.
Figure 2.11: For a given mean, the average covariance is roughly the same across countries. Difference in total covariances stem from a higher variance of the mean times until MRCA across pedigrees in different countries.
Figure 2.12: The variance of the mean across pedigrees in pedigrees built with genealogical data is greater than in the Wright-Fisher. This variance also depends on the particular population we are looking at.
Bibliography


Chapter 3

Y chromosome causing differences in chromatin protein binding profiles between Y introgression lines of Drosophila melanogaster

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(Lene Martinsen, Tim Sackton, and Arvind Sundaram were completely responsible for the experimental design, and for generating the DamID and gene expression data).

3.1 Introduction

Bridges (1916) showed that Drosophila XO males differ from XY males only in that they are sterile, implying that the Y chromosome plays a role in male fertility but is otherwise mostly devoid of functional variation. Indeed, the Y chromosome is genetically degenerate, mainly consisting of large blocks of repetitive DNA with fewer than 20 functional genes (Bachtrog 2013). Despite this, there are multiple lines of evidence that suggest a larger role for the Drosophila Y chromosome in determining phenotype and fitness. The Y chromosome has epigenetic effects on the expression...
of hundreds of X-linked and autosomal genes (Lemos et al., 2008, 2010). Genes regulated by
the Y chromosome (YRV genes) include certain genes for adaptive traits. For example, it has
been suggested that the extremely low level of polymorphism in the African D. melanogaster Y
chromosome is a result of recent selective sweeps, possibly of Y factors that regulate gene expression
elsewhere in the genome (Larracuente and Clark, 2013). These selective sweeps could be the
result of thermal adaptations: David et al. (2005) found that the Y chromosome was responsible
for 50% of the difference in male heat-induced sterility observed between natural populations in
different climactic environments. They could also be the result of differences in wing musculature,
or fatty acid metabolism, the genes for which are differentially expressed in African versus European
populations (Hutter et al. 2008). Y-linked regulatory variation can then lead to Y-linked regulatory
divergence: introgression of D. sechellia or D. simulans Y chromosomes into a common laboratory
D. simulans background affects male reproductive phenotype (Sackton et al. 2011).

A possible mechanism for the influence of the Y chromosome on global gene expression is via
modulating chromatin state. This mechanism was suggested based on a number of different lines
of evidence. First, it is known that the Y chromosome plays a role in position effect variegation, a
process associated with differences in chromatin conformation (Dimitri and Pisano, 1989). Second,
YRV genes are predominantly in repressive chromatin contexts, which implies that these contexts
must play a role in allowing for the modulation of gene expression by the Y chromosome (Sackton
and Hartl, 2013). Finally, Lemos et al. (2010) showed that XXY females that are genetically
identical except for the Y chromosome have substantially different patterns of expression across the
genome. As the Y chromosome is not transcribed in females, this implies that it affects patterns
of expression by modifying the chromatin landscape. Lemos et al. (2010) suggested a possible
mechanism for this modification: the Y chromosome might play the role of a sink for DNA-binding
proteins, affecting the distribution of chromatin regulators across the genome. Indeed, satellite
repeats, also the binding sites of these regulators, are very variable on the Y chromosome.

A series of spatial arguments further substantiate the hypothesis that the Y chromosome is able
to affect the organization of the genome into chromatin compartments. YRV genes are more likely to
be close to each other in the nucleus than non-YRV genes (Sackton and Hartl 2013), implying that

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they might share common regulatory proteins (Naumova and Dekker 2010). YRV genes also tend to be associated with the nuclear lamina (Sackton and Hartl 2013), which is involved in chromatin organization (Gruenbaum et al. 2003). This yields another hypothesis as to the mechanism by which the Y chromosome might influence chromatin state across the genome: it might simply be affecting the spatial configuration of the chromosomes in the nucleus (Sackton and Hartl 2013).

In this study, we explore whether binding of the D1 and Lamin (LAM) proteins is influenced by the Y chromosome. We chose these two proteins as they are abundant in areas where the Y chromosome predominantly exerts its influence: both D1 and LAM mark repressive chromatin contexts (Filion et al. 2010), and LAM is an important component of the nuclear lamina. In other words, we expect these proteins to interact with YRV genes. The D1 protein is an AT hook bearing protein which binds both euchromatic and heterochromatic satellite repeats. The functions of the D1 protein are not entirely clear: the available research shows conflicting results when it comes to the necessity of this protein for development (Aulner et al., 2002; Weiler and Chatterjee, 2009). Based on its similarity with mammalian HMGA proteins, D1 might regulate chromatin structure and the activity of many genes (Reeves and Beckerbauer 2001). Many transcription start sites have AT-rich stretches and D1 might therefore play a role in gene regulation by binding to these sites. Aulner et al. (2002) also suggested that heterochromatic AT-rich regions might serve as storage sites for D1 proteins with the consequence of affecting the distribution of the protein elsewhere in the genome. LAM is an intermediate filament protein and an important component of the nuclear lamina. Located near the inner nuclear membrane and the peripheral chromatin, the nuclear lamina is an extensive protein network that contributes to nuclear structure. Mutated or lost nuclear lamina genes cause a wide range of phenotypes, which indicates that they possess regulatory functions (Gruenbaum et al. 2003).

We screened two African and two European Y introgression lines for variation in chromatin protein binding using DamID in transgenic flies. DamID is a method for large-scale mapping of in vivo protein-genome interactions (Greil et al. 2006). The DamID method makes use of the Escherichia coli protein DNA adenine methyltransferase (DAM), which can be fused to a protein of interest, in this case LAM or D1. When LAM or D1 bind to DNA, the adenines
in DNA surrounding these binding sites are methylated by the DAM protein. Next, adenine-methylated DNA fragments can be isolated, sequenced, and aligned to the *Drosophila melanogaster* reference genome to characterize the pattern of binding. These methylated fragments are indicative of binding, because methylation of adenine occurs naturally only at very low levels in *Drosophila* (Capuano et al., 2014).

We are interested in differences in the binding of the chromatin-related proteins LAM and D1 between the different Y introgression lines, and whether these are correlated with differences in gene expression. More generally, we are interested in knowing whether variation within and between population in Y chromosome sequence could be a non-trivial determinant of epigenetic state.

### 3.2 Materials and Methods

#### 3.2.1 Fly lines, fly husbandry and crossing schemes

Y introgression/substitution lines were established from four geographically distinct *Drosophila melanogaster* populations: two French (Fr188 and Fr89) and two Zambian (Zi238 and Zi2557) (Lemos et al., 2008, 2010). Wild-type males from France and Zambia were crossed with females of the BL4361 fly strain from the Bloomington Drosophila Stock Center and then backcrossed for X generations to obtain different Y chromosomes introgressed into a common isogenic background. The 4361 stock is expected to contain very little genetic variation, and in addition upon receipt was subjected to four additional generations of brother-sister mating to reinforce homozygosity of the genomic background. The 4361 stock inhabits four recessive markers that are used to select the flies with the correct genomic background after backcrossing. These markers are yellow (y1; X chromosome), brown (bw1; chromosome 2), ebony (e1; chromosome 3), and cubitus interruptus and eyeless (ci1, ey1; chromosome 4). All crosses for each Y-chromosome substitution were carried out with 15-20 vials with multiple parents per vial; This resulted in several Y-chromosome substituted males (>30) per line which were subsequently pooled together to give rise to a stable Y-chromosome substitution line.
Flies were kept at 24h light-, temperature-, and humidity-controlled incubators on standard cornmeal medium. For gene expression analyses, newly emerged flies were collected and aged for 3 days at 25°C, after which testes were dissected out and both carcass and testes samples were flash-frozen in liquid nitrogen and stored at -80°C.

Fly dissections to isolate the testes from the rest of the body (carcass) were done under microscope in 1xPBS buffer after the flies were anaesthetized using CO2. Ten flies were dissected and pooled for each sample. We aimed at three biological replicates per sample for both the gene expression data (RNA-seq) and the protein binding data (DamID-seq). For the DamID-seq we also used whole flies that were not dissected.

In order to combine the Y chromosome of interest with the DamID fusion constructs, we set up the following crossing scheme between the Y introgression lines and the DamID transgenic lines:

1. DamID transgenic homozygous virgin females were crossed with males of the Y introgression lines.

2. F1 males (now heterozygous for the DamID fusion construct) were back-crossed to DamID transgenic homozygous virgin females in order to obtain flies that had the Y chromosome of interest and were homozygous for the DamID fusion construct.

3. F2 males were again back-crossed to DamID transgenic homozygous virgin females, but this time in single fly crosses (1 male + 1 female). This was done in order to screen for male flies that were homozygous for the DamID fusion construct, i.e. they would lack the markers on the 3rd and the 4th chromosome that originated from the Y introgression lines (ebony and eyeless, respectively).

4. The males with the correct genotypes were used to establish stable DamID x Yintrogression lines for subsequent DamID-seq and RNA-seq analyses.

The DamID transgenic lines containing the LAM and Dam-only constructs provided by the van Stenseel Lab were homozygous for the DamID construct. The D1 DamID transgenic line from BestGene was heterozygous for the DamID construct so we performed a crossing scheme with a
balancer stock (Bloomington Center stock 9493) to make this line also homozygous before crossing with the Y introgression lines.

### 3.2.2 Generation of transgenic lines

The phiC31 unidirectional site-specific recombination method was used to make transgenic flies containing the protein of interest—D1 and LAM—fused with a DNA adenine methylase (DAM) from *E. coli*. An additional transgenic line containing only the DAM protein (DAM-only) was used as a control. All three lines were produced by Best Gene Inc.; LAM and DAM-only transgenic stocks provided by the van Steensel Lab at the Netherlands Cancer Institute, while the D1 transgenic stock was provided by the Hartl Lab at Harvard University. The BDSC strain #24482 of the FlyC31 system, with insertion site 51C on chromosome 2, was used for the transgenesis. In short, the gene of interest was amplified with primers that have restriction enzyme cut sites. The plasmid vector and the cDNA gene fragment were then digested with two restriction enzymes, and the gene fragment was subsequently ligated into the plasmid with T4 DNA ligase. One Shot chemically competent *E. coli* cells were transformed with the fusion plasmid and plated onto agar plates containing ampicillin for selection of clones. The next day bacterial clones were tested with PCR to check that the protein of interest had ligated into the vector. The clones that gave positive PCR results were chosen and plasmids were isolated with Plasmid DNA Purification Kit (Qiagen). The isolated plasmids were sent to Best Gene Inc. for transgenesis into BDSC lines #24482 embryos. The plasmid vectors—p-attB-NDam[4-HT-intein@L127C]Myc for the transgenesis with the LAM and D1 proteins, and p-attB-Dam[4-HT-intein@L127C]Myc[closed] for the DAM-only controls—were constructed by the van Stenseel Lab (Filion et al., 2010; van Bemmel et al., 2010). These DamID transgenic lines were then crossed with the Y introgression lines.

### 3.2.3 DamID

DamID was performed on the testes, the carcass, and the whole fly as in Vogel et al. (2007) with minor adjustments. In brief, genomic DNA was isolated from the DamIDxY lines by using the DNeasy Blood and Tissue Kit (Qiagen). To obtain the methylated fragments, genomic DNA was
then digested with the restriction enzyme DpnI which cleaves only Gm6ATC sites, not unmethylated sites. Then a double-stranded adaptor oligonucleotide was ligated to the cleaved DNA ends. Following ligation, the DNA is treated with the restriction enzyme DpnII which cuts only unmethylated GATC sites. The sequential use of DpnI and DpnII creates a double selection for methylated DNA fragments: only methylated GATC sequences are cut by DpnI and therefore ligated to the adaptors, and only fragments in which all GATCs are methylated are resistant to degradation by DpnII and can therefore be amplified. The methylated fragments are then amplified by PCR using primers that are complementary to the adaptor sequence. After amplification the fragments are analyzed on an agarose gel. A smear of genomic methylated fragments will be visible on the gel, in addition to bands from amplified methylated plasmid DNA. The PCR products were purified with QIAquick PCR Purification Kit (Qiagen) and used for next-generation sequencing.

### 3.2.4 DamID and Next-Generation Sequencing

The DNA content of the PCR products was measured with Qubit and 200ng (when available) was used as input for the Illumina Next Generation Sequencing protocol using the TruSeq Nano DNA Library Prep Kit. The DNA content of the testis samples was sometimes lower than 200 ng due to limitation of available tissue. The samples were transferred to crimp-cap MicroTube ASA vials for shearing of the DNA in Covaris. The settings used were duty cycle = 10%, intensity = 5, cycles/burst = 200, time = 45 sec as recommended by the Illumina Nano Kit.

### 3.2.5 Gene expression

Total RNA was extracted with TRIzol (Invitrogen) from carcass and testes tissues and treated with DNaseI according to standard protocols. RNA extractions were kept at -80°C. RNA-seq libraries were prepared using the Illumina TruSeq RNA Library Prep Kit v2 according to the manufacturer’s protocol. The samples were sequenced on an Illumina HighSeq 2000/2500 machine.
3.2.6 Bioinformatic analysis

Data availability

DamID sequences and expression data will be deposited in NCBI’s Gene Expression Omnibus.

Data preprocessing

Raw reads from DamID sequencing were processed using Trimmomatic v0.33 to remove sequencing (Illumina) adapters and trim low quality reads. Cleaned data for each sample was further separated into four bins based on the presence of AdRp, AdRt, AdRb adapters or presence of none of these. Double-stranded adaptor oligonucleotides that were used to extract DamIDs were trimmed off using cutadapt v1.4.1 and the reads were aligned to the Fly genome (Dmel_r6.07) using bowtie2. Based on the alignment statistics, reads from AdRt and AdRb bins were not analyzed after this step. Aligned data was converted to bed format using bedtools and extended by (225/212 nts) the average length of the fragments used for preparing the library for sequencing. Location of GATC regions in the fly genome were identified using HOMER v4.7.2 and the reads aligning to these regions in each of the above processed samples were counted using bedtools coverage tool.

Gene expression and Protein binding

Our first aim was to find differentially expressed genes across Y introgression lines. To this end, using our RNA-seq data from testes and carcass tissues, we quantified abundances of non-mitochondrial transcripts using the program kallisto (Bray et al., 2016). The first step was to make a transcriptome index using the flybase Drosophila melanogaster r6.07 transcriptome file. We used the following parameters for each strain: the average fragment length for that strain, 30 as an estimate of the standard deviation for each strain, and 100 bootstrap samples. At the end of this step, we discarded strains with too many undetected transcripts.

We used the library DESeq2 in R (Love et al., 2014) for the analysis of differential expression. This differential expression/binding analysis models the read counts $K_{ij}$ for each gene $i$ and sample $j$ as following a negative binomial distribution:
\[ K_{ij} = NB(s_j q_{ij}, \alpha_i) \]

where \( s_j \) is a sample-specific normalization factor, \( q_{ij} \) is proportional to the concentration of cDNA fragments from the gene in the sample, and \( \alpha_i \) is a dispersion factor which models variability within replicates.

We also use the DESeq2 library in R to analyze differential protein binding.

All code used for the analysis is available at: https://github.com/tsackton/YRV-damID.

3.3 Results

3.3.1 Gene expression

We are interested in identifying differentially expressed genes across Y introgression lines. This will enable us to replicate results from previous studies (Sackton and Hartl, 2013), determine whether or not variation is structured by country, and later correlate patterns of differential expression with patterns of differential binding.

We find that the biggest differences in gene expression are due to tissue type (carcass vs testes). When studying combined carcass and testes data, we identify 2574 statistically significantly differentially expressed genes at the 5% significance level, which is greater than 4 times the number of differentially expressed genes found by running the analysis separately for carcass and testes. As a result, we conservatively choose to study carcass and testes data separately. Conditioning on carcass data, we find 463 statistically significantly differentially expressed genes based on Y line. Analysis of testes data does not show the same level of differential expression, with only 150 statistically significant genes. 15 percent of the carcass data is low count data, relative to only 7.7 percent of the testes data, which implies that the lower number of differentially expressed genes in testes is not due to the testes data being of lower quality. A Fisher’s exact test reveals that there is significant overlap between the differentially expressed genes found in our experiment in both carcass and testes data, and those described in Sackton and Hartl (2013) (p-value < .001).

To test whether Y-linked regulatory variation primarily represents inter-population divergence,
or whether it can arise within the context of a single population, we look at how gene expression variation is structured among lines. To do this, we plot the first two principle components of a PCA of the expression levels of the 463 significantly differentially expressed genes in the carcass data, and the 150 significantly differentially expressed genes in the testes data. Interestingly, this variation is not particularly structured by country. In fact, there is significant intra-population variation (see figures 3.1 and 3.2).

As a second test, we calculate the log$_2$-fold change (MAP), i.e. log$_2$(line1/line2), for all pairs of lines (e.g. Fr188 vs Fr89; Fr188 vs Zi257; etc ... ). These pairwise comparisons reveal that Zi257 is noticeably different from Zi238 in carcass data with 342 significantly differentially expressed genes identified using a Wald test at a 5% significance level. As a final test, we bootstrap the 463 differentially expressed genes by line in the carcass data 10000 times. We then restrict our analysis to only pairs of lines, and run k-means clustering with k=2. Because k-means is based on Euclidean distance, we transform the counts beforehand using a regularized log transformation (Love et al., 2014). We calculate the accuracy of the clustering algorithm in separating lines of same and of different countries over bootstrapped samples of differentially expressed genes, and find that our analysis clearly separates the Zi257 and Zi238 (the two Zambian strains), and Zi257 and Fr188, more than any other pair of lines (with 0 misclassifications).

This level of intra-population difference is unexpected because there are not many SNPs in African populations (Larracuente and Clark, 2013) and because the Y chromosome plays a big part in certain climactic adaptations (David et al., 2005). Because levels of polymorphisms are very low in African populations (Larracuente and Clark, 2013), we may attribute the significant intra-population differences in gene expression in the Zambian lines to other kinds of mutational events, for example differences in the number of repetitive elements. This suggests the potentially important role of repetitive elements in gene regulation. These repetitive elements might affect chromatin state by altering the spatial configuration of chromosomes in the genome, or by modulating the levels of regulatory proteins that can bind elsewhere in the genome. The same pattern is not as apparent in the testes data, perhaps because in the testes data we only bootstrapped over 150 differentially expressed genes.
Figure 3.1: PCA of regularized log transformed gene expression data for the 463 most differentially expressed genes in carcass, colored by country of origin of line (blue for France and red for Zambia).

Figure 3.2: PCA of regularized log transformed gene expression data for the 150 most differentially expressed genes in testes, colored by country of origin of line (blue for France and red for Zambia).
### 3.3.2 Protein binding

It is clear that the Y chromosome affects gene expression, and it is hypothesized that it does so by modifying the distribution of the genome into different chromatin compartments. Using the DamID technique, we are interested in identifying regions of the genome that are differentially bound by D1 and LAM depending on the Y introgression line. We expect both of these proteins to interact with YRV genes.

To identify regions of the genome bound by either LAM or D1, we compared sequencing reads from the LAM or D1 lines to a control with just the DAM protein (not fused to a target protein), and identified bound regions based on a significant likelihood ratio test (LRT) for protein in DESeq2 (full model: ~Protein + Line; reduced model: ~Line). This test reveals that a variable portion of the genome (table 3.1) is bound by each protein across tissue types (testes, carcass, whole fly). We identify between 336 (for testes D1, our lowest quality sample) and 182332 variable sites across the genome, depending on tissue and protein. Binding is much higher for LAM than D1.

We are primarily interested in regions of the genome where binding of either LAM or D1 varies depending on the Y chromosome carried by the transgenic line. To identify these regions, we use another LRT in DESeq2, but now we hope to detect a significant line by protein interaction, meaning that the effect of D1 or LAM vs DAM-only varies among lines (full model: ~Protein + Line + Protein:Line; reduced model: ~Protein + Line). In carcass, testes, and whole-fly tissues, we are able to identify regions of differential binding using a LRT test (see table 3.2). LAM binding is in general positively correlated across tissue types. In particular line by tissue subsets, LAM binding is negatively correlated to D1 binding (see figure 3.3). This holds even conditioning on heterochromatin state being ‘BLACK’, one of the repressive heterochromatin states described by Filion et al. (2010).

<table>
<thead>
<tr>
<th></th>
<th>Carcass</th>
<th>Testes</th>
<th>Whole fly</th>
</tr>
</thead>
<tbody>
<tr>
<td>D1</td>
<td>7222 (5.06%)</td>
<td>336 (0.086%)</td>
<td>40179 (14.10%)</td>
</tr>
<tr>
<td>LAM</td>
<td>140514 (40%)</td>
<td>118484 (36.14%)</td>
<td>182332 (47.91%)</td>
</tr>
</tbody>
</table>

Table 3.1: Binding Results. We report the number of methylated GATC sites at the 0.1% significance level for each tissue-protein combination. As the number of low-counts is variable, in parentheses we express the number of significant sites as a percentage of non-low count data.
Table 3.2: **Differential Binding Results.** We report the number of differentially methylated GATC sites at the 0.1% significance level for each tissue-protein combination. As the number of low-counts is variable, in parentheses we express the number of significant sites as a percentage of non-low count data. Testes LAM data for line 238 was missing, so differential binding analysis was done on the remaining three lines.

<table>
<thead>
<tr>
<th></th>
<th>Carcass</th>
<th>Testes</th>
<th>Whole fly</th>
</tr>
</thead>
<tbody>
<tr>
<td>D1</td>
<td>4113 (6.35%)</td>
<td>4351 (16%)</td>
<td>45 (.04%)</td>
</tr>
<tr>
<td>LAM</td>
<td>52874 (19.9%)</td>
<td>2974 (4%)*</td>
<td>268 (.63%)</td>
</tr>
</tbody>
</table>

Figure 3.3: Heatmap of log2-fold pairwise correlations of regions of protein binding for each protein by tissue by line combination.
It is important to note some aspect of these data which could affect our results. Both our pre- and post- sequencing results suggest that D1 testes samples are of notably low quality, so we expect not to be able to draw many conclusions from this data. Also, the number of differentially expressed lines in whole fly is low in comparison to testes and carcass, especially in the case of LAM binding. As differential binding is positively correlated for the same protein in carcass and testes data, we do not expect lower counts in whole fly data.

We identify differentially bound regions by looking for stretches of more than 25 contiguous significant p-values, using a 5% significance level. We look for contiguous p-values because we expect binding to extend over multiple GATC sites. According to this criterion, one of the most differentially bound loci is the Stellate locus (Ste) on the X chromosome, which is differentially bound by LAM in whole fly data. Negative regulatory interaction exists between this locus and the Suppressor of Stellate Su(Ste) locus on the Y chromosome. More precisely, the silencing of the Ste locus is mediated by dsRNA \cite{Aravin2001}. It has been hypothesized that the Ste-Su(Ste) system is dispensable, and evolved as a self-maintaining parasitic system \cite{Bozzetti1995}. We do not find Ste to be significantly differentially expressed in different Y introgression lines. However, it is difficult to determine statistical significance for this gene because expression levels are (as expected) very low.

Another region of clear differential binding is the 5S rRNA locus on chromosome 2R, which is differentially bound both by LAM in testes and by D1 in carcass data (see figure\textsuperscript{3.4}). Interestingly, the sign of the $\log_2$-fold change of D1 in carcass data and LAM in testes data at this locus is not consistent across lines. 5S rRNA acts in collaboration with rRNA products derived from blocks located on the X and Y chromosomes to form the ribosome. Therefore, we would expect there to be correlation in the expression levels of all of these rRNAs. The rRNA genes in the 45S block of \textit{Drosophila melanogaster} are particularly AT-rich \cite{Tautz1988}, so we might expect involvement of D1. Interestingly, previous research has shown that rDNA contributes to global chromatin regulation \cite{Paredes2009}, and that variation in copy number affects genome-wide expression patterns \cite{Paredes2011}.

Both of the Ste locus and the 5S rRNA locus consist of Y-related tandem repeats, which suggests
that some of the observed differential binding could potentially be driven by variation in Y-linked transcription of non-coding RNAs. However, this is not the only role of the Y chromosome: we also found a stretch of DNA of about 100 kbp located near the centromere on chromosome 2 to be differentially bound by LAM in whole fly data (2L:22409449..22508017). The presence of this long differentially bound stretch of DNA allows us to conclude that multiple different kinds of genomic regions are influenced by the Y chromosome, not just tandem repeats.

**The heterochromatic sink model**

There are many mechanisms by which the Y chromosome might be able to affect chromatin state across the genome. One proposed model is the heterochromatic sink model (Lemos et al., 2010), which suggests that the Y chromosome acts as a protein sink, influencing the quantity of protein available to bind at other sites in the genome. In its simplest form, this model yields a very clear prediction: we would expect some strains to show significantly lower levels of binding than other strains. In fact, an ANOVA F-test rejects the hypothesis that the mean log₂-fold change of D1 binding in comparison to DAM is the same across all strains (p-value < .001). These means are...
0.6 in line 188, .22 in line 89, .09 in line 257, and .13 in line 238 (they are all positive because we expect D1 to bind on average more than DAM). This allows us to conclude that there are large scale differences in binding among the four lines, which is consistent with the heterochromatic sink model, while not providing definitive evidence for it. However, the results of the F-test are at least suggestive that there might be some global or higher order models.

3.4 Discussion

It is known that the Y chromosome is able to influence gene expression throughout the genome. In this study, we have provided more evidence for Y induced differential expression, and the YRV genes we identified overlap significantly with those previously discovered. We found that variation in gene expression is not particularly structured by country, which given the expected differences between countries based on Y-associated adaptations (such as thermal adaptations), implies that intra-population variation is high and overlaps with inter-population variation. Also, because there are very few SNP differences in African strains, these results argue that variation in repetitive regions on the Y chromosome likely play an important role in modulating transcriptional activity across the whole genome.

Differential binding does occur, most notably in regions of tandem repeats, and in centromeric regions. This implies that the Y chromosome probably affects chromatin binding across the genome in a variety of different ways, and that in some cases it is very likely that RNA plays a mediating role. Significant differences in mean binding of D1 across Y introgression lines points to global models, like the heterochromatic sink model.

Future work will involve correlating regions of differential expression with regions of differential binding to provide further insight into the mechanism by which the Y chromosome affects expression on the X chromosome and the autosomes.
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